

{log} User's Manual

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ABSTRACT This is the second edition of the user's manual for *{log}*, a Constraint Logic Programming language that embodies the fundamental forms of set designation and a number of primitive operations for set management.

The *{log}* interpreter is written in Prolog and the full Prolog code of the interpreter is freely available at the *{log}* WEB page <http://www.clpset.unipr.it/setlog.Home.html>.

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What's new

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- Introduction of concurrency when $\{log\}$ is used as a theorem prover (Sect. 11).
- Definition of a few new rewrite rules (Sect. 11).
- New execution options that enable or disable the new rewrite rules (Sect. 11).
- When the above items are combined, $\{log\}$ can considerably increase its efficiency when used as a theorem prover.
- New user commands (`timeout/1`, `t_solve/1`, `t_solve/3`, `p_t_solve/1`, `prover_all_strategies/1`) to exploit the above new features (Sect. 11).
- Definition of the `tryp` execution configuration that can be passed as the fifth argument to `setlog/5`, thus enabling concurrency also when $\{log\}$ is used from Prolog (Sect. 15.1).
- New section on execution of state machines (Sect. 13.3).
- Sections 3.6 and 3.7 have been rewritten.
- New Sect. 11 on using $\{log\}$ as an automated theorem prover.
- Bug fixed in `groundsol` (Sect. 3.2).
- Bug fixed in `!` (cut, Sec. 14.1).

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- New user commands `vcace` and `vcgce` (Sect. 13.5.1).
- Concerning the specification of state machines (Sect. 13), now user-defined theorems are divided into theorem statement and proof, whereas the latter must have a specific form (Sect. 13.2).
- Bug fixed in the VCG concerning well-formedness of operation's heads.

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- When working with types, it is not necessary to declare the type of the quantified variables appearing in RQ (Sect. 12.3).
- Bug fixed concerning how RQ are typechecked.

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- When the VCG is used to generate verification conditions, users can discharge them by calling commands accepting proving options and a timeout (Sect. 13.4).
- Bug fixed in the processing of intensional sets.

1 Introduction

$\{log\}$ (read ‘set-log’) is a Constraint Logic Programming language that embodies the fundamental forms of set designation and a number of primitive operations for set management [1, 4, 5, 7].

Sets are designated primarily by the explicit enumeration of all its elements (*extensional sets*), using set terms. Sets can contain not only atoms as their elements, but also other sets (*nested sets*), with no restriction over the level of set nesting.

The language provides a number of basic primitive operations for set management, such as `=` (equality), `in` (set membership), `un` (union), `inters` (intersection), etc. $\{log\}$ can also deal with binary relations and partial functions through most of the standard relational operators, such as `dom` (domain) and `comp` (relational composition). Given that binary relations and partial functions are sets of ordered pairs they can be freely combined with sets, thus providing a uniform treatment for all these concepts.

Furthermore, $\{log\}$ provides *Restricted Universal Quantifiers* (RUQ) and *intensional sets*, that is sets defined by a property rather than by enumerating all their elements.

$\{log\}$ inherits much of standard Prolog: its syntax (apart a few minor changes), the user interaction modality, input/output facilities, some extra-logical features (e.g., arithmetic). Throughout the manual, we assume the reader is familiar with Prolog and programming with Prolog techniques, as well as with the general principles and notation of Constraint Logic Programming languages. Moreover, for some part of the $\{log\}$ language (e.g., its syntax) we will only describe those features that really differ from standard Prolog. For other parts (e.g., input/output, arithmetic) we will completely rely on the corresponding standard Prolog facilities. Finally, for all the formal results concerning $\{log\}$ (e.g., its logical and procedural semantics, the constraint solving mechanism) we refer the reader to the $\{log\}$ specific papers listed in the Bibliography section.

The $\{log\}$ interpreter is written in standard Prolog and has been tested using SWI-Prolog (last releases) and can be ported to any Prolog system implementing standard Prolog with very limited effort.¹

The first version of the $\{log\}$ interpreter was developed by Agostino Dovier and Enrico Pontelli, under the supervision of Eugenio Omodeo and Gianfranco Rossi, as part of their work to obtain the “Laurea” degree at the Department of Mathematics and Computer Science of the University of Udine in 1991. Later on, the $\{log\}$ interpreter was revised at various times by Gianfranco Rossi, who is still maintaining the current version of the interpreter. More recently (circa 2015), Gianfranco Rossi and Maximiliano Cristiá extended $\{log\}$ in various aspects, adding new features for dealing with binary relations, partial functions, Cartesian products, and Restricted Intentional Sets.

The Prolog code of the $\{log\}$ interpreter is available at the $\{log\}$ web page:

<http://www.clpset.unipr.it/setlog.Home.html>

At the same page, you can find also the PDF file of this manual, various $\{log\}$ library files containing the $\{log\}$ definitions of operations on sets, binary relations and lists not provided as built-in in $\{log\}$, a file containing a number of simple preprocessing rules (“filtering rules”) that may help constraint solving, and a few sample programs and applications written in $\{log\}$.

¹As a minor difference with standard Prolog, note that the precedence of the module qualification operator (`:`)—see [op/3](#) and [Defining a meta-predicate](#), in SWI-Prolog’s on-line user’s manual—has been changed from 600 to 350.

2 Using $\{log\}$

Assume the $\{log\}$ interpreter (Prolog source code) has been saved into a file named `setlog.pl`. To start working with the interpreter, invoke Prolog and then load the $\{log\}$ interpreter, e.g., by using `consult/1`:

```
?- consult('setlog.pl').
```

The $\{log\}$ interpreter is loaded into the Prolog program database. While loading, the interpreter tries to consult four additional files from the working directory (see also the `setlog_config/1` built-in predicate in Sect. 15.1):

- `setlog_rules.pl`: this file provides a number of additional constraint rewriting rules that are not strictly necessary for the solver to work correctly, but can be useful to simplify processing of the input formulas.
- `size_solver.pl`: this file provides the implementation of a constraint solving procedure that allows you to extend the basic constraint solver of $\{log\}$, making it able to deal with cardinality constraints in a correct and complete way; without loading this file you can still use cardinality constraints but the solver is no longer guaranteed to be a decision procedure (see Sect. 8).
- `setlog_tc.pl`: this file provides a number of predicates that allow you to activate (optional) type checking for your programs; if this file is not loaded no type checking can be performed (see Sect. 12).
- `setlog_vcg.pl`: this file provides predicates that permit to work with state machines as in formal notations such as B and Z (see Sect. 13).

Once loaded, there are two ways to use $\{log\}$: interactively, much as Prolog itself; and as a Prolog predicate. We will illustrate both of them with a simple example. To access the interactive environment execute the following goal:

```
?- setlog.
```

and $\{log\}$ will show you its prompt:

```
{log}=>
```

Now you can give it goals much as in the Prolog environment. For example, you can ask $\{log\}$ to solve the following formula (as regards terminology, note that saying “executing the goal G ” is the same as saying “asking $\{log\}$ to solve formula G ”):

```
{log}=> un({1},{2},A).
```

in which case $\{log\}$ answers:

```
A = {1,2}
```

and asks you if you want another solution.

The same goal can be executed from the Prolog environment, e.g., by using the built-in predicate `setlog/1` (see Sect. 15.1 for more information):

```
?- setlog(un({1},{2},A)).
```

making Prolog to print:

```
A = {1,2}
```

In the interactive mode, you can leave the `{log}` environment by issuing:

```
{log}=> halt.
```

and you can re-enter the `{log}` environment by simply issuing again `setlog`. Note that, in the current implementation, a few run-time errors possibly detected by Prolog while executing the `{log}` interpreter may force execution to leave the `{log}` environment. To re-enter `{log}`, call `setlog`.

2.1 Loading `{log}` libraries

Libraries can be loaded in any order and in any moment. Library predicates are dealt with as other user defined predicates. The standard `{log}` library can be loaded from the `{log}` environment by issuing:

```
{log}=> consult_lib.
```

The same can be done from the Prolog environment by issuing

```
?- consult_lib.
```

All other libraries, e.g., the library `'setloglibpf.slog'` concerning partial functions, must be consulted using the `{log}` predicate `add_lib/1`. For example:

```
{log}=> add_lib('setloglibpf.slog').
```

The same can be obtained from the Prolog environment by issuing

```
?- setlog(add_lib('setloglibpf.slog')).
```

See Section 16 for the complete list of the predicates defined in the standard `{log}` library.

2.2 Dealing with `{log}` programs

`{log}` programs are much like Prolog programs; that is, a collection of clauses saved in a file. For example, assume the following clause is saved in file `p.pl`:

```
un12(A) :- un({1},{2},A).
```

Then you can load it into the `{log}` environment with the `consult/1` predicate as follows:

```
{log}=> consult('p.pl').
```

and then you can use the clauses defined in it as follows:


```
{log}=> un12({1,2,3}).
```

in which case `{log}` answers no because the union of sets `{1}` and `{2}` is not equal to the set `{1,2,3}`.

While consulting, the interpreter shows on the standard output the number of the clause it is currently reading or an error message if a syntax error is detected. All clauses previously stored in the `{log}` program database are removed.

User defined clauses currently stored in the `{log}` program database can be printed out on the standard output by executing:

```
{log}=> listing.
```

These clauses can be completely removed by executing:

```
{log}=> abolish.
```

Note that both predicates `abolish` and `listing` ignore library clauses that have been added by either `consult_lib` or `add_lib`; thus, library clauses cannot be removed nor listed.

`{log}` programs can be loaded also by using `consult/2`. Precisely:

```
{log}=> consult('file.slog',mute).
```

loads the program in `file.slog` just like `consult('file.slog')` but without showing the number of the clause it is currently reading; while:

```
{log}=> consult('file.slog',app).
```

loads the program in `file.slog` just like `consult('file.slog')` but without removing clauses previously stored in the program database. `{log}` programs can be loaded also directly from the Prolog environment by issuing:

```
?- setlog_consult('file.slog').
```

whose behavior is exactly the same as `consult('file.slog',mute)`.²

2.3 Asking for help

Finally, simple help facilities are provided in the form of built-in predicates:

- `help/0` (or `setlog_help/0` from the Prolog environment) provides general help information on `{log}`;
- `h/1` (both from `{log}` and from the Prolog environment) provides more detailed information on `{log}`, according to its parameter: `h(syntax)` for `{log}` syntactic conventions; `h(constraints)` for `{log}` constraints; `h(builtins)` for `{log}` built-in predicates; `h(lib)` for `{log}` standard library predicates; `h(prolog)` for Prolog predicates for accessing `{log}` from the Prolog environment; `h(all)` to get all available help information.

²At present, no other facility is provided to consult, remove, or listing a program in `{log}`. In particular, it is not allowed to consult a program stored in `file` by using the syntax `[file]`, as usual in Prolog. Moreover, there is no support for reconsulting a program. The standard Prolog predicates `abolish/2` and `listing/1` are not provided for now.

3 Solving formulas with extensional sets

An extensional set is a set whose elements are enumerated. For example, $\{1, a, \text{hello}\}$ is an extensional set with three elements. Some of the elements of an extensional set can be other extensional sets. For example, $\{a, b\}$ is an element of the following extensional set $\{51, \{a, b\}\}$. Elements inside an extensional set can be of any sort (or type or class), as shown in the previous examples.

The most simple extensional set is the *empty set* noted in $\{log\}$ as $\{\}$. The second most simple extensional set is the *singleton set*, noted in $\{log\}$ as $\{e\}$, where e is its single element. Then we can ask $\{log\}$ whether the empty set is equal to a singleton set:

$$\{log\} \Rightarrow \{\} = \{1\}.$$

in which case the answer is, obviously, no.

As in mathematics, $\{log\}$ extensional sets can contain variables. In $\{log\}$, as in Prolog, variables are denoted by identifiers starting with an uppercase letter or an underscore. Then, we can ask $\{log\}$ to solve the following equation:

$$\{log\} \Rightarrow \{X\} = \{1\}.$$

where X is a variable. In this case the answer is:

$$X = 1$$

Note that:

$$\{log\} \Rightarrow \{x\} = \{1\}.$$

results in a no answer because x is a constant not equal to 1.

A more interesting formula is the following:

$$\{log\} \Rightarrow \{X, Y\} = \{2, 1\}.$$

because it has two solutions:

$$\begin{aligned} X &= 2, Y = 1 \\ X &= 1, Y = 2 \end{aligned}$$

that $\{log\}$ is able to find by exploiting *set unification* [8].

$\{log\}$ also provides a notation (not used in mathematics) to define sets. The expression $\{x / A\}$ represents the set $\{x\} \cup A$. Then, A must denote a set. So, for instance, we can write $\{1 / \{a / \{\}\}\}$ which represents the set $\{1\} \cup (\{a\} \cup \emptyset)$ which is equal to the set $\{1, a\}$. Given this obvious equality, $\{log\}$ allows a more user-friendly notation: we can write $\{1, a / \{\}\}$ instead of $\{1 / \{a / \{\}\}\}$; and $\{1, a / \{\}\}$ can be further simplified as $\{1, a\}$. When combined with the fact that variables can be sets, this notation provides a new level of expressiveness to the language. For instance, it is interesting to ask $\{log\}$ for the solutions of the following formula (which again calls into play set unification):

$$\{log\} \Rightarrow \{X/A\} = \{6, 7, 8\}.$$

as it has six:

- $_1 X = 6, A = \{7, 8\}$
- $_2 X = 6, A = \{6, 7, 8\}$
- $_3 X = 7, A = \{6, 8\}$
- $_4 X = 7, A = \{6, 7, 8\}$
- $_5 X = 8, A = \{6, 7\}$
- $_6 X = 8, A = \{6, 7, 8\}$

Note that, for instance, the second solution states that $\{6 / \{6, 7, 8\}\}$ is equal to $\{6, 7, 8\}$ which is true in virtue of the so-called *absorption property* of set theory [4]. Recall that $\{6 / \{6, 7, 8\}\}$ can be written as $\{6, 6, 7, 8\}$ where the presence of duplicate elements becomes evident.

Note how the number of solutions increases if we want to identify more elements in the set. For example, the following equation:

$$\{\log\} \Rightarrow \{X, Y/A\} = \{6, 7, 8\}.$$

has 30 solutions, among which:

- $$\begin{aligned} X &= 6, Y = 7, A = \{8\} \\ X &= 6, Y = 7, A = \{7, 8\} \\ X &= 6, Y = 6, A = \{6, 7, 8\} \end{aligned}$$

In $\{x_1, \dots, x_n / A\}$, x_1, \dots, x_n is called *element part* and A is called *set part*. It is very important to remark that since the set part of an extensional set can be a variable (representing any finite extensional set), then $\{\log\}$'s extensional set constructor allows users to write *unbounded finite sets*. In effect, an expression such as $\{x / A\}$ represents a finite but *unbounded* set as the set denoted by A can have any number of elements.

In addition to extensional set terms, sets can also be denoted by other types of set terms, specifically, Cartesian products (Sect. 4), intensional set terms (called RIS, Sect. 5), and integer intervals (Sect. 9).

3.1 Set operators

$\{\log\}$ supports all the classic set operators. All set operators are given as predicates. Then, for instance, we can ask $\{\log\}$ to find a value for A in:

$$\{\log\} \Rightarrow \text{inters}(\{1\}, \{2\}, A).$$

making $\{\log\}$ to answer

$$A = \{\}$$

as A must be equal to the intersection between $\{1\}$ and $\{2\}$.

Table 1 lists all the set operators available in $\{\log\}$ as predicates. As can be seen, most operators have their own negation. Although $\{\log\}$ implements negation (see Sect. 3.4), it is always advisable to use the negated predicates.

All the arguments of all these predicates can be variables and set terms. Even the in and nin predicates admit sets as the first argument because in $\{\log\}$ set elements can be sets. For example:

OPERATOR	$\{log\}$	MEANING
set	set(A)	A is a set
equality	$A = B$	$A = B$
membership	$x \text{ in } A$	$x \in A$
union	un(A,B,C)	$C = A \cup B$
intersection	inters(A,B,C)	$C = A \cap B$
difference	diff(A,B,C)	$C = A \setminus B$
subset	subset(A,B)	$A \subseteq B$
disjointness	disj(A,B)	$A \parallel B$
strict subset	ssubset(A,B)	$A \subset B$
symmetric difference	sdiff(A,B,C)	$C = A \triangle B$
NEGATIONS		
set	nset(A)	A is not a set
equality	$A \text{ neq } B$	$A \neq B$
membership	$x \text{ nin } A$	$x \notin A$
union	nun(A,B,C)	$C \neq A \cup B$
intersection	ninters(A,B,C)	$C \neq A \cap B$
difference	ndiff(A,B,C)	$C \neq A \setminus B$
subset	nsubset(A,B)	$A \not\subseteq B$
disjointness	ndisj(A,B)	$A \nparallel B$

Table 1: Set operators available in $\{log\}$

$\{log\} \Rightarrow \{1\} \text{ in } \{2,a,\{1\}\}.$

makes $\{log\}$ to answer *yes*.

We believe all set operators are self-explanatory although *set* and *nset* require some clarifications. Users seldom need to indicate that something is a set when writing $\{log\}$ code. In general, $\{log\}$ automatically infers the *sort* of variables by analyzing the formulas in which they participate. Hence, predicates *set* and *nset* are generally used internally by $\{log\}$. Users may see a *set* predicate as part of the answer given by $\{log\}$ for some formulas—see an example in the next section. In addition to sorts, $\{log\}$ defines a type system, see Section 12.

All these operations are dealt with as *constraints*, and, hence, they can be used with no concern about the instantiations of their arguments. The predicates listed in Table 1, along with those listed in Tables 3, 5, 6, 8, and 9, represent all and only the *atomic constraints* available in $\{log\}$.

3.2 Answers to queries and the *groundsol* predicate

The first answer to the following query:

$\{log\} \Rightarrow \text{diff}(\{1\}, A, B).$

is the following:

```
A = {1/_N1}
Constraint: subset(B,{1}), 1 nin _N1, un(B,_N1,_N2), 1 nin _N2, set(_N2),
          1 nin B, set(_N1), disj(B,_N1), set(B)
```

where $_N1$ is a variable name automatically generated by $\{log\}$ and Constraint is a list of *constraints* that the variables returned by $\{log\}$ must verify. Variables automatically generated by $\{log\}$ are called *new* or *fresh* variables. $\{log\}$ will include many fresh variables in its answers. In general, the answer returned by $\{log\}$ is composed of:

- A (possibly empty) list of equalities of the form $v = t$ where v is a variable and t a term which can contain other variables.
- A (possibly empty) list of constraints which contain variables.

The constraints occurring in the computed answer are called *irreducible constraints*.

The above answer is interpreted as follows: B is the result of computing the set difference between $\{1\}$ and A if and only if *there exist* sets $_N1$ and $_N2$ such that $A = \{1/_N1\}$, B is a subset of $\{1\}$, 1 doesn't belong to $_N1$, $_N2$ is the union of B and $_N1$, 1 doesn't belong to $_N2$ nor to B and B and $_N1$ are disjoint. Hence, $_N1$ and $_N2$ are existentially quantified variables—where the existential quantifier is implicit. This interpretation can be easily and naturally generalized to every answer returned by $\{log\}$.

In many academic papers about $\{log\}$ it has been shown that the conjunction of constraints returned by $\{log\}$ is always satisfiable. In other words, there are always values that can be bound to the free variables appearing in the returned answer satisfying the conjunction of equalities and constraints. In many answers it is quite easy to find these values but this is not always the case. When there are no integer variables involved, a possible value for set variables is the empty set. That is, if set variables are substituted by the empty set the conjunction of the returned equalities and constraints is satisfied. For example, let's substitute B, $_N1$ and $_N2$ in the above answer by the empty set:

```
A = {1/{}}
```

```
Constraint: subset({}, {1}), 1 nin {}, un({}, {}, {}), 1 nin {}, set({}),
          1 nin {}, set({}), disj({}, {}), set({})
```

It's clear that $A = \{1\}$ and that all the constraints are true. For example, $\text{subset}(\{\}, \{1\})$, interpreted as $\emptyset \subseteq \{1\}$, is obviously true; and $1 \text{ nin } \{\}$, interpreted as $1 \notin \emptyset$, is also evidently true.

As we have said, $\{log\}$ may return several answers to a given goal (just press letter 'y' when $\{log\}$ asks you for more solutions). We have proved that *the disjunction of all these answers is equivalent to the original formula*. Since an answer may contain variables, it represents a (possibly infinite) set of ground (or concrete) solutions of the original formula. A *ground solution* is a solution where variables appear only at the left-hand side of the equalities composing a $\{log\}$ answer. For example, we have just seen that $A = \{1\}$, $B = _N1 = _N2 = \{\}$ is a ground solution of the first answer returned by $\{log\}$ after executing $\text{diff}(\{1\}, A, B)$. Whereas the bindings $A = \{1, 2\}$, $B = \{\}$, $_N1 = _N2 = \{2\}$ represent another ground solution. So by changing 2 by any number different from 1 we get one more solution. When the initial formula belongs to one of the fragments of set theory for which $\{log\}$ implements a decision procedure, $\{log\}$ returns a finite number of answers. Hence, in these cases, *the disjunction of the answers*

returned by $\{log\}$ is a finite representation of all the (possibly infinite) ground solutions of the initial formula.

Just above we showed how to get a concrete solution from an answer returned by $\{log\}$. Basically, we substituted all set variables by the empty set. However, when integer variables are involved, finding a ground solution satisfying the computed answer is more complex. For these cases, and even for complex formulas not involving integer variables, $\{log\}$ provides the predicate `groundsol` which forces $\{log\}$ to produce ground solutions.

Consider the following examples.

```
{log}=> groundsol.
{log}=> diff({1},A,B).
```

```
A = {1},
B = {}
```

```
{log}=> X in A.
```

```
X = n0,
A = {n0}
```

When `groundsol` is active, $\{log\}$ binds set and integer variables to (ground) sets and integer numbers, respectively. For the remaining free variables, $\{log\}$ binds constants of the form $n\langle number \rangle$, where *number* is an integer number starting from zero.

To restore the default behavior issue `nogroundsol`.

`groundsol` also works (somewhat differently) when $\{log\}$ is running in typechecking mode (see Section 12).

Hereafter, if not explicitly mentioned, all sample queries to $\{log\}$ will be intended to be issued not in `groundsol` mode.

3.3 Considerations on set membership and not membership

It is easy to prove the following:

$$x \in A \Leftrightarrow \exists B : A = \{x\} \cup B \wedge x \notin B \quad (1)$$

This equivalence is used by $\{log\}$ when it finds a constraint of the form $X \text{ in } A$. In fact $\{log\}$ transforms $X \text{ in } A$ into $A = \{X/_N1\} \ \& \ X \text{ nin } _N1$, where $_N1$ is a fresh variable, which is aligned with the semantics of the $\{_/_\}$ set constructor.

On the other hand, when $\{log\}$ finds a constraint of the form $A = \{X/B\}$ it *does not* assume $X \text{ nin } B$. This may lead to a degraded performance as $\{log\}$ will open two computation branches: one in which $X \text{ nin } B$ holds, and another one in which $B = \{X/_N1\} \ \& \ X \text{ nin } _N1$ holds. Then, in general, $\{log\}$ will need twice the time to solve a formula including $A = \{X/B\}$ than the same formula but including $X \text{ in } A$ instead of the latter.

Observe that in most situations, what you want to say is $X \text{ in } A$ rather than $A = \{X/B\}$, for some B . In these situations it is advisable to use the former over the latter. There are situations, however, where B appears in some other constraint of the formula, meaning that the scope of B is not the sub-formula representing the membership relation like in (1), but the whole formula.

CONNECTIVE	$\{log\}$	MEANING
conjunction	&	\wedge
disjunction	or	\vee
negation	neg	\neg
implication	implies	\Rightarrow
not implication	nimplies	\nRightarrow
negation as failure	naf	\neg

Table 2: Propositional connectives available in $\{log\}$

In these situations conjoining X nin B might not be what the formula is intended to state. So $\{log\}$ leaves this to the user's discretion.

3.4 Introducing formulas

In this section we will show how to write some of the formulas accepted by $\{log\}$.

The propositional connectives available in $\{log\}$ are listed in Table 2. Formulas are built from these connectives in the usual way. Arguments of the connectives can be either atomic constraints, restricted quantifiers (see Sect. 6), user-defined or built-in predicates, as well as other $\{log\}$ formulas, built in the same way.

As can be seen, in $\{log\}$ conjunction is written with the & character (instead of the comma as in Prolog). Then, in asking $\{log\}$ to solve the formula:

$\{log\} \Rightarrow un(\{1/B\}, \{j\}, A) \ \& \ j \ in \ B.$

it answers:

$B = \{j/_N1\},$
 $A = \{1, j/_N1\}$
 Constraint: $j \ nin \ _N1, \ set(_N1)$

Logical disjunction is also available in $\{log\}$ by means of the or connective (instead of the semicolon as in Prolog). The same formula given above but using disjunction in place of conjunction:

$\{log\} \Rightarrow un(\{1/B\}, \{j\}, A) \ or \ j \ in \ B.$

has two solutions:

$A = \{j, 1/B\}$
 Constraint: $set(B)$

$B = \{j/_N1\}$
 Constraint: $set(A), \ j \ nin \ _N1, \ set(_N1)$

where A can be any set in the second solution.

Disjunction and conjunction can be freely combined to form complex formulas. As conjunction has higher precedence than disjunction use parenthesis to write the right formula. Disjunction is managed as in Prolog, i.e., through non-determinism and backtracking. Hence, if a variable name appears in two or more disjuncts then it actually represents a different variable in each disjunct.

3.5 Negation and the let construct

Negation is available through predicates `naf` and `neg`. `naf` computes the classical “Negation as Failure” of Prolog: `naf(G)`, fails if `G` has a solution, and succeeds otherwise. `neg` computes the propositional negation of its argument, possibly applying Boolean laws. In particular, if the argument is a `{log}` constraint, then the language itself provides its negation. For example, `neg(X in A & Z nin C)` becomes `X nin A or Z in C`.

Both forms of negation, however, may work incorrectly in general. More specifically, `naf` works well only when variables in the formula are properly instantiated; `neg` may not work well when the negated formula contains unrestricted existentially quantified variables *inside the formula*.

As an example of the latter, consider the following user-defined predicate

```
singleton_set(X) :- X = {Y}.
```

which is true when `X` is a singleton set. In `{log}`, as in Prolog, variables that occur only in the body of a clause (e.g., `Y`) are all implicitly existentially quantified (excluding “local” variables occurring in intensional sets—Sect. 5—and restricted quantifiers—Sect. 6). Hence, solving the body of this clause amounts to solve the following formula:

$$\exists X : (\exists Y : X = \{Y\}) \quad (2)$$

If we want also the negative version of this predicate, then we can define a new predicate, say `notsingleton_set(X)`, which is true whenever `X` is not a singleton set (e.g., `{}`, `{1,2}`, `1,...`). Hence, the clause body of `notsingleton_set` should express the formula:

$$\exists X : \neg (\exists Y : X = \{Y\}) \equiv \exists X : (\forall Y : X \neq \{Y\}) \quad (3)$$

Observe the existentially quantified variable inside the formula to be negated. The definition of `notsingleton_set(X)` using `neg` is as follows:

```
notsingleton_set(X) :- neg(X = {Y}).
```

In this case, however, solving the clause body amounts to solve the formula:

$$\exists X : (\exists Y : X \neq \{Y\}) \quad (4)$$

Note the difference between the formula obtained by using `neg` (i.e. (4)) and the actual negation of (2) (i.e. (3)). Thus, for example,

```
{log} => notsingleton_set({}).
```

correctly answers yes, but issuing

```
{log} => notsingleton_set({1}).
```

we get

```
true Constraint: S neq {_N1}
```


instead of no.

Alternatively, one can use `naf` for expressing negation instead of `neg`. In this case, however, the formula obtained by solving the clause body of `notsingleton_set` is:

$$\forall X, Y : X \neq Y \quad (5)$$

since, in general, all variables in a predicate which is negated through `naf` are dealt with as universally quantified. Thus, for example,

```
{log} => notsingleton_set({}).
{log} => notsingleton_set({1}).
```

correctly answer yes and no, respectively, but issuing

```
{log} => notsingleton_set(S).
```

we get a no answer which is evidently wrong.

Note that implementing the other form of formula (3), i.e. $\exists X : (\forall Y : X \neq \{Y\})$, is not feasible in the current version of `{log}`, since the general form of universal quantification required by this formula is not supported yet.

`singleton_set` can be written, however, in such a way that negating it by means of `neg` works correctly.

```
singleton_set(X) :- size(X,1).
```

where `size` computes the cardinality of its first argument (see Sect. 8). Note that the body of this clause does not contain any new existentially quantified variable. In this way:

```
notsingleton_set(X) :- neg(size(X,1)).
```

is equivalent to:

```
notsingleton_set(X) :- nsize(X,1).
```

which coincides with the logical negation of `singleton_set`. Nevertheless, in general, is not always possible to find a `{log}` encoding of a given mathematical formula whose negation is correctly computed by `neg`.

The `let` construct. Say you want to compute the result of the following set expression:

$$(A \cup B) \cap C$$

In `{log}` it can be done as follows:

```
un(A,B,U) & inters(U,C,Res)
```

which is interpreted as:

$$A \cup B = U \wedge U \cap C = Res \quad (6)$$

See that we need to introduce two new variables: *U* to get a partial result; and *Res* to get the desired result. Note that *U* is simply a “name” for $A \cup B$. Besides, note that *U* is a *shared* variable

in the sense that it is present in two (or more) constraints. Now, say that you want to state that Res is different from $(A \cup B) \cap C$, i.e.:

$$A \cup B = U \wedge U \cap C \neq Res \quad (7)$$

In $\{log\}$ using neg in a direct way, i.e., by issuing $neg(un(A,B,U) \ \& \ inters(U,C,Res))$, we actually get:

$$\neg (A \cup B = U \wedge U \cap C = Res) \equiv A \cup B \neq U \vee U \cap C \neq Res$$

which does not correspond to the intended formula (7).

Hence, for these cases (which appear frequently in $\{log\}$) the language provides the `let/3` construct. We can use it to capture the fact that we are naming a subexpression as follows:

$$let([U], un(A,B,U), inters(U,C,Res))$$

Then, $\{log\}$ rewrites the above formula as:

$$un(A,B,U), inters(U,C,Res)$$

However, its negation:

$$neg(let([U], un(A,B,U), inters(U,C,Res)))$$

is rewritten as:

$$un(A,B,U) \ \& \ ninters(U,C,Res)$$

which is the intended formula (recall that `ninters` is the negated version of `inters`, see Table 1).

The general form of `let` is as follows:

$$let(list_of_vars, \psi, \phi)$$

where:

- *list_of_vars* is a list of distinct variables not appearing anywhere else in the formula.
- ψ is a conjunction of *functional predicates* and equalities of the form $X = t$, where X is a variable and t a term. A functional predicate is a predicate that behaves as a function for its last argument. For example, union, intersection, set difference, etc. are functional predicates. The last argument is called *result*. The `is` predicate is functional but on its first argument. The variables appearing in *list_of_vars* must be the results of the functional predicates and the variables at the right-hand side of the equalities in ψ . A variable in *list_of_vars* can appear as the result of only one functional predicate or at the right-hand side of only one equality³.
- ϕ is a $\{log\}$ formula.

³The current version of $\{log\}$ doesn't implement all these restrictions, so users are responsible of enforcing them.

`{log}` implements two simple rewrite rules for `let`:

$$\begin{aligned} \text{let}(\text{list_of_vars}, \psi, \phi) &\longrightarrow \exists \text{list_of_vars}(\psi \wedge \phi) \\ \text{neg}(\text{let}(\text{list_of_vars}, \psi, \phi)) &\longrightarrow \exists \text{list_of_vars}(\psi \wedge \text{neg}(\phi)) \end{aligned}$$

The `let` construct is useful in general when we have to compute the negation of a conjunction where there are shared variables among its constraints. Consider the following `{log}` formula:

$$S = \emptyset \wedge X \in S$$

If we apply `neg` to it we get:

$$S \neq \emptyset \vee X \notin S$$

which is not correct because $S = \emptyset \wedge X \in S \equiv X \in \emptyset$ and so the negation should be just $X \notin \emptyset$. The problem arises from the fact that S is shared among $S = \emptyset$ and $X \in S$. We can solve the problem by using `let`:

$$\text{let}([], S = \{\}, X \text{ in } S)$$

In which case the negation is:

$$S = \{\} \ \& \ X \text{ nin } S$$

Negation of user-defined predicates. When using `neg`, if its argument is a user-defined predicate, then the user must provide its negation by means of another user-defined predicate. If the head symbol of a user-defined predicate is p , with arity $n \geq 0$, then its negation is a user-defined predicate named n_p , with arity n . That is the prefix $n_$ is added to p . In this way `{log}` considers that n_p is the negation of p whereas the latter is the negation of the former: $\text{neg}(p)$ is n_p and $\text{neg}(n_p)$ is p . Therefore, users are advised to refrain from using the prefix $n_$ in other contexts. As an example, by using `n_singleton_set`, instead of `notsingleton_set`, as the name of the predicate defined above, then one can apply directly `neg` to the positive predicate, as for instance:

$$\{\text{log}\} \Rightarrow \text{neg}(\text{singleton_set}(\{1\})).$$

If the solver does not find any clause defining n_p when calling $\text{neg}(p(t_1, \dots, t_n))$, it will use $\text{naf}(p(t_1, \dots, t_n))$ in its place and, if $p(t_1, \dots, t_n)$ is not ground, then it will print the warning message: `using unsafe negation`.

Implication. Finally, note that implication is defined in `{log}` as follows:

$$P \text{ implies } Q \text{ :- } \text{neg}(P) \text{ or } Q.$$

This means that `implies` works correctly much as `neg` does. `{log}` also introduces `nimplies` as follows:

$$P \text{ nimplies } Q \text{ :- } P \ \& \ \text{neg}(Q).$$

If `implies` or `nimplies` are used with user-defined predicates, consider that you'll have to declare the negation of those user-defined predicates because, as explained above, `{log}` doesn't automatically compute the negation of user-defined predicates. A common pattern when `{log}` is used to prove the unsatisfiability is:

$$\neg (p \Rightarrow q)$$

which `{log}` rewrites as:

$$p \wedge \neg q$$

Then, if q is a user-defined predicate, a predicate named `n_q` representing the negation of q must be in scope.

`neg` is also implicitly used when solving some constraints on Restricted Intensional Sets (Sect. 5.1).

3.6 Proving unsatisfiability (i.e., proving theorems)

`{log}` can be used to prove that a given formula is unsatisfiable. The following is a trivial example.

```
{log}=> {X,Y} = {Z} & X neq Y.
```

```
no
```

As can be seen, `{log}` answers `no` meaning the formula is unsatisfiable (i.e., there are no values for X , Y and Z that can make the formula true).

The following is a more interesting example as we are proving a property of set union.

```
{log}=> neg(un(A,B,C) implies un(B,A,C)).
```

```
no
```

Clearly, if the above formula is unsatisfiable *for all finite sets A , B and C* , then the inner formula `(un(A,B,C) implies un(B,A,C))` is valid (i.e., it's a theorem) *for all finite sets A , B and C* . So we have just proved that union is commutative *for all finite sets*. However, have a look at Sect. 3.5 to see some limitations of `neg`.

Hence, if you want to check if p is a theorem, call `{log}` on $\neg p$ and wait for a `no` answer.

In general, the capability of `{log}` to prove unsatisfiability depends on whether or not the formula belongs to a class of formulas for which `{log}` implements a decision procedure. `{log}` implements a decision procedure for formulas involving extensional sets, the operators of Table 1, and the first two connectives of Table 2. In coming sections we will show other fragments of set theory for which `{log}` implements decision procedures.

Although the use of `neg` in the above goal is safe, it can also be written without `neg` as follows:

`un(A,B,C) & nun(B,A,C) .`

Indeed, note that $\neg(p \Rightarrow q) \equiv \neg(\neg p \vee q) \equiv (p \wedge \neg q)$. As `nun` is exactly \neg `un`, then both formulas are equivalent.

Precisely, the introduction of other connectives besides conjunction and disjunction may compromise decidability, as indicated in Sect. 3.5. For example, as shown in that section, if negation is used in combination with existentially quantified variables, `{log}` may be not able to work correctly. Furthermore, if the user-defined predicates possibly involved in the formula are defined through recursive definitions, the proof of the formula may be non-terminating. Also, if some extra-logical built-in predicates are involved in the formula, the solver is not guaranteed to work correctly whenever variables are not enough instantiated.

Other cases in which `{log}` may be not able to behave as a decision procedure, e.g., when intensional sets are involved (Sect. 5.1), will be pointed out in next sections.

When `{log}` is used to prove unsatisfiability we say that it's used as an *automated theorem prover*. Proving unsatisfiability can be computationally very hard. The *prover* mode of operation (see next section) can help on that. Nevertheless, see Sect. 11 for a detailed account of user commands that might overcome this difficulty.

3.7 Modes of operation

Users can run `{log}` in one of two modes of operation: the *prover* mode and the *solver* mode. The default mode when `{log}` is loaded is the prover mode. Users can switch from one mode to the other by issuing:

`{log}=> mode(solver) .`

or

`{log}=> mode(prover) .`

Although it is hard to predict in advance which mode of operation will be the best for a given formula, as a rule of thumb, we can say that if you want to use `{log}` as a programming language, then the first choice would be the solver mode; and if you want to use it as an automated prover, then use it in prover mode.

In general, in prover mode `{log}` will be more efficient in concluding that the formula is unsatisfiable, than in solver mode. The prover mode has more advanced options that can further improve `{log}`'s efficiency when attempting to prove unsatisfiability, as is explained in Section 11. In turn, the solver mode is better when the formula passed to `{log}` is supposed to be satisfiable. In general, in these cases `{log}` will return solutions with fewer constraints and more equalities, than in solver mode. This means that if users want to use `{log}` as a prototyping environment, they should use it in solver mode.

For example, executing the following goal in prover mode:

`{log}=> subset(X,{a,b}) .`

makes `{log}` to return the following answer:

```
true
Constraint: subset(X,{a,b}), set(X)
```

meaning that the input formula is anyway satisfiable. If the same goal is executed in solver mode, instead, `{log}` will return the following four solutions:

```
X = {a,b}
X = {a}
X = {b}
X = {}
```

Note that if `goalsol` is activated when in prover mode, the `subset` goal above will return only one ground solution whereas in solver mode it will return the same four solutions.

4 Solving formulas with binary relations

A binary relation is a set of ordered pairs. If X and Y are two sets then any set R such that $R \subseteq X \times Y$ is a binary relation. Given that binary relations are sets (of ordered pairs) then `{log}` can be used to work with formulas involving binary relations [12]. Such formulas, however, may involve not only set operators (cf. Table 1) but also *relational operators*. For this purpose, `{log}` introduces a rich set of relational operators, such that it can determine the satisfiability of any formula including them. Besides, `{log}` provides a new set term, `cp(A,B)`, whose semantics is the Cartesian product (CP) between sets A and B [11]. Note that a Cartesian product is a binary relation.

For example, asking `{log}` to solve the following formula:

```
{log}=> dom(R,{a}).
```

makes the solver to return the most general binary relation whose domain is the set $\{a\}$. This relation is given as follows:

```
R = {[a,Y]/S}
Constraint: comp([a,a],S,S), [a,Y] nin S, rel(S)
```

There are several things to comment about this answer. R is given as an extensional set containing the ordered pair $[a, Y]$ because R must contain at least one ordered pair (because it has a not-empty domain) whose first component must be a , while the second component can be anything—which is represented by making the second component to be a variable.

Observe that ordered pairs are noted with square brackets. Then, $[a, b]$ represents the ordered pair (a, b) . Note that, $[a, b] = [c, d]$, if and only if $a = c$ and $b = d$. In this manual, when writing mathematics we will use parenthesis to note ordered pairs, but we will use square brackets when we show `{log}` code. `{log}` provides the predicate `pair(t)` (resp., `npair(t)`) to constrain a term t to be (resp., not to be) an ordered pair.

Moreover, the set part of R (i.e., S) is *constrained* to be a binary relation by means of the predicate `rel(S)`. Indeed, `rel` forces its argument to be a set of ordered pairs. However, constraining S to be a relation is not enough for the correctness of the solution. The domain

of S must be a subset of $\{a\}$. This is forced by the constraint $\text{comp}(\{[a, a]\}, S, S)$. In effect, $\text{comp}(Q, T, U)$ means $U = Q \circ T$, that is U is the result of the relational composition between Q and T . Formally:

$$Q \circ T = \{(x, z) \mid \exists y : (x, y) \in Q \wedge (y, z) \in T\}$$

Then, it can be shown that $\text{dom}(\{(a, a)\} \circ T) = \{a\}$, thus guaranteeing that $\text{dom}(\{(a, y)\} \cup T) = \{a\}$, for any y .

Finally, note that the constraint $[a, Y] \text{ nin } S$ is generated by the solver to avoid possibly infinite computations due to the application of the absorption property, which might generate set terms with infinitely many occurrences of the same element. In fact, the formula $R = \{x/S\} \ \& \ x \text{ nin } S$ ensures that S cannot contain any occurrence of x .

Since Cartesian products are binary relations, a term $\text{cp}(A, B)$ can be passed to any predicate expecting a binary relation as its argument. Hence, we can use Cartesian products with relational operators, for example, as follows:

$$\{\log\} \Rightarrow \text{dom}(\text{cp}(\{a/A\}, B), \{a\}).$$

making $\{\log\}$ to return $A = \{\}$ and $A = \{a\}$.

In turn, since binary relations are sets of ordered pairs, they can be built by means of the same set constructors described in Section 3 and they can be used in the same places as any other set terms. In particular the empty binary relation is denoted with $\{\}$. Furthermore, formulas involving relational operators are built as we shown in Section 3.4 (i.e., by means of $\&$, or and the other logical connectives). Besides, they can be freely combined with formulas involving set operators. For example:

$$\begin{aligned} \{\log\} \Rightarrow \text{dom}(R, \{a/B\}) \ \& \ [b, X] \text{ in } R. \\ \{\log\} \Rightarrow \text{cp}(A, B) = \{\} \ \& \ \text{ran}(R, B). \end{aligned}$$

are formulas combining set and relational operators and making use of the extensional set and Cartesian product constructors.

It is very important to remark that, as can be seen in the previous formula, not only the relation is a *set* in exactly the same sense of the sets introduced in Section 3, but also its domain. This clearly shows that $\{\log\}$ allows for a completely uniform treatment of sets and binary relations (including Cartesian products).

Note that Cartesian products can be used to assert that a binary relation is of a particular *type*. If you want binary relation R to be of type $A \times B$ you can state:

$$\{\log\} \Rightarrow \text{subset}(R, \text{cp}(A, B)).$$

So, for instance, $\{\log\}$ will answer no if the following formula is provided:

$$\{\log\} \Rightarrow \text{subset}(R, \text{cp}(A, \{1, 2\})) \ \& \ R = \{[X, 1], [Y, 9]\}.$$

but it will find solutions if the following one is given:

$$\{\log\} \Rightarrow \text{subset}(R, \text{cp}(A, \{1, 2\})) \ \& \ R = \{[X, 1], [Y, Z]\}.$$

See more about types in $\{\log\}$ in Section 12.

OPERATOR	$\{log\}$	MEANING
binary relation	$rel(R)$	R is a binary relation
domain	$dom(R, A)$	$dom R = A$
range	$ran(R, A)$	$ran R = A$
composition	$comp(R, S, T)$	$T = R \circ S$
inverse	$inv(R, S)$	$S = R^{-1}$
identity relation	$id(A, F)$	$id A = F$
domain restriction	$dres(A, R, S)$	$S = A \triangleleft R$
domain anti-restriction	$dares(A, R, S)$	$S = A \triangleleft R$
range restriction	$rres(R, A, S)$	$S = R \triangleright A$
range anti-restriction	$rares(R, A, S)$	$S = R \triangleright A$
overriding	$oplus(R, S, T)$	$T = R \oplus S$
relational image	$ring(A, R, B)$	$B = R[A]$
NEGATIONS		
binary relation	$nrel(R)$	R is not a binary relation
domain	$ndom(R, A)$	$dom R \neq A$
range	$nran(R, A)$	$ran R \neq A$
composition	$ncomp(R, S, T)$	$T \neq R \circ S$
inverse	$ninv(R, S)$	$S \neq R^{-1}$
identity relation	$nid(A, F)$	$id A \neq F$
domain restriction	$ndres(A, R, S)$	$S \neq A \triangleleft R$
domain anti-restriction	$ndares(A, R, S)$	$S \neq A \triangleleft R$
range restriction	$nrres(R, A, S)$	$S \neq R \triangleright A$
range anti-restriction	$nrare(R, A, S)$	$S \neq R \triangleright A$
overriding	$noplus(R, S, T)$	$T \neq R \oplus S$
relational image	$nring(A, R, B)$	$B \neq R[A]$

Table 3: Relational operators available in $\{log\}$ (R, S and T are binary relations)

4.1 Relational operators

Table 3 lists all the relational operators, along with their negations, available in $\{log\}$ as atomic constraints. In turn, Table 4 gives the mathematical definition of each relational operator given in Table 3. All the arguments of all these predicates can be variables and set terms, but not RIS terms (Sect. 5.1) nor integer intervals (Sect. 9).

As with set operators, we believe all relational operators are self-explanatory. Same considerations mentioned for set and nset apply for rel and $nrel$. That is, in general, users do not need to indicate that something is a binary relation because $\{log\}$ automatically infers this fact. Thus, strictly speaking, the definitions in the first part of Table 3 should be extended by conjoining the predicates rel for all the relations occurring as arguments in the operators. For example, the precise meaning of $dom(R, A)$ is $rel(R) \wedge dom R = A$. Of course, similar observations apply to the negative versions of these predicates. For example, the precise meaning of $ndom(R, A)$ is $nrel(R) \vee dom R \neq A$. For example:

$$\{log\} \Rightarrow ndom(\{[a, 1]/R\}, \{a\}).$$

has two solutions:

OPERATOR	DEFINITION
domain	$\text{dom } R = \{x \mid \exists y : (x, y) \in R\}$
range	$\text{ran } R = \{y \mid \exists x : (x, y) \in R\}$
composition	$R \circ S = \{(x, z) \mid \exists y : (x, y) \in R \wedge (y, z) \in S\}$
inverse	$R^{-1} = \{(y, x) \mid (x, y) \in R\}$
identity relation	$\text{id } A = \{(x, x) \mid x \in A\}$
domain restriction	$A \triangleleft R = \{(x, y) \mid (x, y) \in R \wedge x \in A\}$
domain anti-restriction	$A \triangleleft R = \{(x, y) \mid (x, y) \in R \wedge x \notin A\}$
range restriction	$R \triangleright A = \{(x, y) \mid (x, y) \in R \wedge y \in A\}$
range anti-restriction	$R \triangleright A = \{(x, y) \mid (x, y) \in R \wedge y \notin A\}$
overriding	$R \oplus S = (\text{dom } S \triangleleft R) \cup S$
relational image	$R[A] = \text{ran}(A \triangleleft R)$

Table 4: Definition of relational operators

$R = \{[_N3, _N2]/_N1\}$ Constraint: $\text{set}(_N1), _N3 \text{ neq } a$

$R = \{_N2/_N1\}$ Constraint: $\text{set}(_N1), \text{npair}(_N2)$

where the second one simply states that R is not a binary relation because it contains something that is not an ordered pair.

4.2 Partial functions

A *partial function* is a binary relation where no two ordered pairs share the same first component. Formally, f is a partial function if and only if f is a binary relation and:

$$\forall x, y_1, y_2 : (x, y_1) \in f \wedge (x, y_2) \in f \Rightarrow y_1 = y_2 \quad (8)$$

Therefore, partial functions are a subset of binary relations. This means that $\{log\}$ can also be used to find solutions for formulas involving partial functions [9]. These formulas, are built as formulas involving binary relations plus the addition of the predicates listed in Table 5.

Differently from `rel`, users *must* explicitly include a `pfun` predicate for all those binary relations they want to be partial functions. $\{log\}$ will only automatically assert that F is a partial function if it appears as an argument of one of the predicates implementing partial function operators, as shown in the first part of Table 5. For example, the following formula is unsatisfiable if F is intended to be a partial function but it is satisfiable for a binary relation:

$$\{log\} \Rightarrow \text{dom}(F, \{a\}) \ \& \ [a, Y1] \text{ in } F \ \& \ [a, Y2] \text{ in } F \ \& \ Y1 \text{ neq } Y2.$$

Then, $\{log\}$ gives as a first solution:

$$\begin{aligned} F &= \{[a, Y1], [a, Y2]/G\} \\ \text{Constraint: } &[a, Y2] \text{ nin } G, \text{ comp}(\{[a, a]\}, G, G), [a, Y1] \text{ nin } G, \\ &Y1 \text{ neq } Y2, \text{ rel}(G) \end{aligned}$$

for that formula but it answers no for the following:

OPERATOR	$\{log\}$	MEANING
partial function	$pfun(F)$	F verifies (8)
function application	$apply(F, X, Y)$	$F(X) = Y$
domain	$dompf(F, A)$	$dom(F, A)$
composition	$comppf(F, G, H)$	$comp(F, G, H)$
domain restriction	$drespf(F, G, H)$	$dres(F, G, H)$
NEGATIONS		
partial function	$npfun(F)$	F does not verifies (8)
function application	$napply(F, X, Y)$	$F(X) \neq Y$
domain	$ndompf(F, A)$	$dom F \neq A$

Table 5: Partial function operators available in $\{log\}$ (F, G and H are partial functions)

$\{log\} \Rightarrow pfun(F) \ \& \ dom(F, \{a\}) \ \& \ [a, Y1] \text{ in } F \ \& \ [a, Y2] \text{ in } F$
 $\ \& \ Y1 \text{ neq } Y2.$

Note that, as observed for relational operators, strictly speaking, the definitions of the predicates listed in Table 5 should include the constraints $pfun$ and $npfun$ that are automatically added by $\{log\}$. Thus, for instance, the precise meaning of $dompf(F, A)$ is $pfun(F) \wedge dom F = A$; while the precise meaning of $ndompf(F, A)$ is $npfun(F) \vee dom F \neq A$.

$\{log\}$ provides also a less restrictive form of function application through the predicate $applyTo$. $applyTo(R, X, Y)$ is true if R is a binary relation containing exactly one pair whose first component is X and whose second component is Y . Formally, $applyTo(R, x, y)$ holds iff:

$$(x, y) \in R \wedge (\forall y_1 : (x, y_1) \in R \Rightarrow y_1 = y) \quad (9)$$

This means that one can use the $applyTo$ on a binary relation which is not a function but which is a function only for certain values of its domain. For example:

$\{log\} \Rightarrow applyTo(\{[1, 2], [2, 3], [2, 4]\}, 1, Y).$

makes $\{log\}$ to answer $Y = 2$, even if $\{[1, 2], [2, 3], [2, 4]\}$ is not a function. Conversely:

$\{log\} \Rightarrow applyTo(\{[1, 2], [2, 3], [2, 4]\}, 2, Y).$

makes $\{log\}$ to answer no, since $\{[1, 2], [2, 3], [2, 4]\}$ is not a function in 2.

Observe that the negations of predicates $comppf$, $drespf$, and $applyTo$ are not available (at present) as $\{log\}$ constraints, but they are provided as library predicates by the libraries `setloglibpf.slog` and `setloglib_tc.slog` (as such, they take the names `n_comppf`, `n_drespf`, and `n_applyTo`, respectively).

4.3 Decidable formulas involving binary relations

$\{log\}$ behaves as a semi-decision procedure for the *theory of finite, unbounded binary relations* (including Cartesian products). This means that in general $\{log\}$ will return the right answer but for some formulas it will not return; or it will return some solutions and then will block; or

it will return an infinite number of solutions. In any case the solutions are correct but it will fail in proving that some formulas are unsatisfiable.

More precisely, such undesired behaviors may appear when `comp` constraints are involved, either explicitly or implicitly. The following are two simple formulas showing non-termination of $\{log\}$:

$$\begin{aligned} \{log\} \Rightarrow & \text{comp}(\{[X,Z]/R\}, \{[Z,Y]/S\}, R) . \\ \{log\} \Rightarrow & \text{comp}(R, S, \{[X,Z]/S\}) . \end{aligned}$$

Actually, with the first goal $\{log\}$ enters an infinite loop producing no answer, while with the second one it returns an infinite number of solutions. Intuitively, the problem with the above formulas is caused by the presence of `comp` constraints where the first or second argument shares a variable with the third argument. Generally speaking, in these cases, $\{log\}$ is not able to compute a finite representation for the possible solutions.

The sharing of a variable between the third and the other two arguments of a `comp` constraint can be also indirect, through some other constraint. For instance:

$$\{log\} \Rightarrow \text{comp}(R, S, \{[X,Z]/U\}) \ \& \ \text{un}(S, T, U) .$$

Moreover, the sharing can be generated during constraint solving, even starting with a formula that initially does not contain any such situation.

In our experience, however, all these “unpleasant” formulas occur very rarely in practice.

It is worth noting that the presence of a variable shared in a `comp` constraint does not necessarily implies non-termination. For instance, the following formula:

$$\{log\} \Rightarrow \text{comp}(\{[X,Z]/R\}, \{[Z,Y]/S\}, R) \ \& \ \text{id}(A, R) .$$

contains one such unsafe variable sharing, but nevertheless $\{log\}$ terminates, returning a finite number of solutions.

5 Intensional sets

Intensional sets, also called *set comprehensions*, or *set-builder notation*, are sets described by a property whose elements must satisfy rather than by explicitly enumerating their elements. Intensional sets are widely recognized as a key feature to describe complex problems.

The main way to express intensional sets in $\{log\}$ is by means of the so called *Restricted Intensional Sets* (RIS) [10]. Another way is by using *general intensional sets* (GIS). The next subsection deals with RIS, while GIS are briefly described in subsection 5.2.

5.1 Solving formulas with Restricted Intensional Sets

A Restricted Intensional Set (RIS) denotes a *finite* intensional set. In the language of mathematics a RIS is noted as:

$$\{x : D \mid F(x) \bullet P(x)\} \tag{10}$$

where x , called *control variable*, is a bound variable whose scope is the RIS itself; D , called *domain*, is a set; F , called *filter*, is a formula; and P , called *pattern*, is an expression. The semantics of a

RIS is the following:

$$\{y : \exists x(x \in D \wedge F(x) \wedge y = P(x))\} \quad (11)$$

that is, the elements of the RIS are of the form $P(x)$ for all those $x \in D$ satisfying $F(x)$.

In $\{log\}$ a RIS such as (10) is written as follows:

```
ris(X in D, [], F(X), P(X))
```

where D can be any kind of set except for `cp` and variable intervals (see Section 9); F is a $\{log\}$ formula and P is a $\{log\}$ term. The second argument (i.e., `[]`) will be explained shortly. A $\{log\}$ RIS term can be more complex but for the moment we will focus on this simpler construction.

In the current version, $\{log\}$ admits RIS in all the set operators of Table 1 and `dompf` (only as first argument) and `pfun`. This means that RIS cannot be used as arguments or as part of arguments passed in to relational operators (cf. Tables 3 and 5).

The following formula uses a RIS to find out if N is a prime number or not (`int(m,n)` is a set term denoting the integer interval $[m,n]$, see Section 7 for further details):

```
{log}=> N > 1 & MD is N div 2 &
      ris(X in int(2,MD), [], 0 is N mod X, X) = {}
```

The idea is to check if the set of proper divisors of N (i.e., $\{x : [1, MD] \mid 0 = N \bmod x\}$) is empty or not. Then, if N is bound to, say, 20, $\{log\}$ answers no; but if it is bound to 101 it answers $N = 101$, $MD = 50$.

Note that in the last example the pattern is the control variable (i.e., X). When this is the case the pattern can be omitted. Similarly, when the second argument is the empty list it can be omitted. Thus, the RIS above can be written more concisely as:

```
ris(X in int(2,MD), 0 is N mod X)
```

It is important to observe that predicates occurring in a RIS formula can be not only any of the predefined predicates available in $\{log\}$, but also any user-defined predicate. Since in some cases the solver needs to negate the RIS formula, then, in general, it is necessary that the negated versions of all the user-defined predicates occurring in the RIS formula are in scope. In this regard, remember that (see Sect. 3.4) if p is the name of a user-defined predicate with arity n , the negated version of p must be named n_p . If the solver does not find any clause defining n_p , it will use `na p`, possibly printing the warning message using `unsafe negation`.

The control variable of a RIS term is an existentially quantified variable whose scope is the RIS term itself—in other words, the control variable is *local* to the RIS term. In its current form, however, $\{log\}$ doesn't check whether or not this variable is used outside the RIS term. It's the user's responsibility to avoid such name clashes which may make $\{log\}$ to produce unexpected behaviors.

5.1.1 Parameters and the functional section

Now we are going to explain the meaning of the second argument of a RIS term and through it we will present one more argument of RIS terms. Say you want to specify a function mapping sets to their cardinalities provided they are greater than one. Then, you can use the following RIS:

$$CF = \text{ris}(S \text{ in } D, [C], C > 1, [S, C], \text{size}(S, C))$$

In effect, CF is the set of ordered pairs of the form $[S, C]$ where S belongs to D , C is the cardinality of S and C is greater than one. Hence, CF is a function as is a set of ordered pairs where no two pairs have the same first component. The following are two formulas that can be proved to hold using $\{log\}$:

$$D = \{\{X\}, \{Y, Z\}\} \ \& \ CF = \text{ris}(S \text{ in } D, [C], C > 1, [S, C], \text{size}(S, C)) \ \& \ CF = \{\}.$$

$$[\{1, 2\}, N] \text{ in } \text{ris}(S \text{ in } D, [C], C > 1, [S, C], \text{size}(S, C)).$$

yielding $Z = Y$ and $N = 2$, respectively, as part of their computed answers.

Note that in CF the second argument is no longer the empty list but the list containing variable C . This kind of variables are called *parameters*. Parameters are local to the RIS where they appear⁴. The semantics of a parameter is an existentially quantified variable. Then, the semantics of CF is given by the following intentional set:

$$\{y : \exists s(\exists c(s \in D \wedge |s| = c \wedge c > 1 \wedge y = (s, c)))\} \quad (12)$$

The second argument of a RIS term is called the *parameters list*. In the parameters list you can introduce as many parameters as you need. All of them have the same semantics.

In general, $\{log\}$ may give wrong answers to formulas including RIS with parameters. As an example, the following formula:

$$R = \{\{1, a\}, \{1, b\}, \{3, a\}, \{2, c\}, \{3, b\}\} \ \& \ A = \{1, 2\} \ \& \ \text{ris}(X \text{ in } A, [Y], [X, Y] \text{ in } R, [X, Y]) = \{\}.$$

is found to be satisfiable, whereas it is clearly not. In fact, the given RIS defines the domain restriction of a binary relation R with respect to a set A , and with the given values for R and A it represents the set $S = \{\{2, c\}, \{1, a\}, \{1, b\}\}$.

However, if parameters are used to get the ‘results’ of some predicates, then they are safe. This is what we did with C in the first RIS at the beginning of this subsection, because we use it to get the cardinality of S through the predicate $\text{size}(S, C)$. In doing so we placed $\text{size}(S, C)$ in the fifth argument of the RIS term and not as part of the filter. By placing $\text{size}(S, C)$ in the fifth argument $\{log\}$ can treat it in a different way than a regular filter predicate; had we placed it as a regular filter constraint $\{log\}$ might have given wrong answers.

The fifth argument of a RIS term is called the *functional section*. In the functional section you can place a conjunction of constraints each of which captures its ‘result’ in a parameter declared in the RIS. This means that only constraints that behave as functions can be placed in the functional section. We call these constraints *functional predicates*. For example, assuming A is a parameter, you cannot place $\text{size}(A, N)$ in the functional section because for a given N there are many sets whose cardinality is N . In other words, size behaves as a function only w.r.t. its second argument. Along the same lines, if A and B are parameters, $\text{un}(A, B, C)$ is not allowed in

⁴As with control variables, $\{log\}$ doesn’t check whether or not the formula respects this restriction; hence, it’s the user’s responsibility to avoid using parameters outside of RIS terms.

the functional section because it depends on two parameters; if only A is a parameter, $\text{un}(A, B, C)$ is not allowed neither because for any given sets B and C there are many A for which $\text{un}(A, B, C)$ is true; but $\text{un}(D, C, A)$ can be placed in the functional section because for any given sets D and C there is only one A for which $\text{un}(D, C, A)$ is true.

As can be seen, parameters and the functional section in a RIS behave as the `let` construct (see Sect. 3.5). In fact we have the following:

$$\text{ris}(X \text{ in } A, [\text{vars}], \phi, p, \psi) = \text{ris}(X \text{ in } A, [], \text{let}([\text{vars}], \psi, \phi), p)$$

5.1.2 Parameters and control expressions

Some times we need parameters but we cannot express what we want with functional predicates. If we persist in using parameters the formula becomes unsafe. However, `{log}` offers another safe way that avoids many of those unsafe parameters.

In fact, some parameters can be avoided by using *control expressions* instead of a control variable. A control expression is an expression of the following forms:

- Any nested closed list whose elements are all distinct variables (e.g., $[X]$, $[X, [Y], Z]$, etc.);
- $[X|Y]$, where X and Y are different variables;
- $\{X/Y\}$, where X and Y are different variables.

In all cases the variables in the control expression are variables bound to the RIS.⁵ Then, for example, the RIS in the formula with a wrong answer in the previous subsection can be alternatively written without using parameters but using a control expression:

$$R = \{[1, a], [1, b], [3, a], [2, c], [3, b]\} \ \& \ A = \{1, 2\} \ \& \\ \text{ris}([X, Y] \text{ in } R, X \text{ in } A) = \{\}.$$

where the RIS pattern is omitted as is expected to be the control expression. In this case, `{log}` will correctly find that the formula is unsatisfiable.

As another example, if R is a set and we want the subset of R whose elements are ordered pairs of integer numbers such that their first components are greater than or equal to the second components, we can use the following RIS:

$$\text{ris}([X, Y] \text{ in } R, X \geq Y)$$

Observe that this set cannot be expressed with the set and relational operators of Sections 3 and 4 nor with functional predicates (because \geq is not such a predicate).

As the above RIS do not introduce parameters, every formula including them will always return the right answer (i.e., those formulas are *safe* because they lay inside the decision procedure).

When control expressions are used in place of control variables, only the elements of the domain of the RIS that unify with the control expression are processed (all the others are simply ignored). For example, consider the RIS above where R is instantiated with $\{1, [0, 3], [5, 1]\}$. Then, we have:

⁵The variables in control expressions are subjected to the same locality restriction of control variables and parameters.

$$\{[5,1]\} = \text{ris}([X,Y] \text{ in } \{1,[0,3],[5,1]\}, X \geq Y)$$

because 1 is ignored as it does not unify with $[X,Y]$; $[0,3]$ does not pass the filter; and $[5,1]$ is the only element of the domain of the RIS which unifies with the control expression and passes the filter.

5.1.3 Encoding sets of structured elements

Control expressions can be used to extract elements with particular structures. The above is such an example but elements with more complex structure can also be considered. In effect, the structure of an element can be given by an appropriate nesting of functors. For example, $p(X, q(X, Y, Z))$, where p and q are functors and X, Y and Z are variables. Such an element can be encoded as follows: $[p, [X, [q, [X, Y, Z]]]]$. Then, if we want the subset of A whose elements are of the form $p(X, q(X, Y, Z))$ we can use the following RIS:

$$\text{ris}([P, [X1, [Q, [X2, Y, Z]]]] \text{ in } A, P = p \ \& \ Q = q \ \& \ X1 = X2)$$

where $X1$ and $X2$ are introduced because all the variables in a control expression must be different from each other.

Furthermore, if we also want elements of the form $p(E)$ we can use union:

$$\begin{aligned} &\text{un}(\text{ris}([P, [X1, [Q, [X2, Y, Z]]]] \text{ in } A, P = p \ \& \ Q = q \ \& \ X1 = X2), \\ &\quad \text{ris}([P, [E]] \text{ in } A, P = p), \\ &\quad \text{Result}) \end{aligned}$$

5.1.4 Safe patterns

As we have said at the beginning of this section, a pattern in a RIS term is a $\{log\}$ term. However, for a formula to be safe the patterns involved in the RIS participating in the formula must verify a couple of conditions. In order to precisely state those conditions, we need the following definitions.

Definition 5.1 (Bijective pattern) *Let $\{x : D \mid F(x) \bullet P(x)\}$ be a RIS, then its pattern is bijective if $P : \{x : x \in D \wedge F(x)\} \rightarrow Y$ is a bijective function, where Y is the set of images of P .*

Definition 5.2 (Co-injective patterns) *Two patterns, P and Q , are said to be co-injective if for any x and y , if $P(x) = Q(y)$ then $x = y$.*

Then, for a formula to be safe all its patterns must be bijective and pairwise co-injective.

Checking whether a formula verifies these conditions is, in general, not decidable. Hence, $\{log\}$ does not perform this check: checking whether the patterns of the RIS included in input formulas are bijective and pairwise co-injective or not is left to the user's responsibility. Fortunately, at least the following patterns *always* verify Definitions 5.1 and 5.2:

- terms of the form $[X, f(\dots, X, \dots)]$, where X is the control expression and f is any function;
- terms of the form $[f(\dots, X, \dots), X]$, where X is the control expression and f is any function;

- the formula contains patterns of either form but not a mix of them.

As an example, executing the following goal:

```
{log}=> [4,N] in ris(X in D,[Y],X>=0,[X,Y],Y is X*X).
```

where the RIS contains a safe pattern, correctly answers

```
N = 16,
D = {4/_N1}
Constraint: 4 nin _N1, set(_N1)
```

On the other hand, executing the goal:

```
{log}=> ris([X,Y] in R,true,X) = {1}.
```

where the RIS pattern is not a safe one, will yield the following answer:

```
R = {[1,_N2]/_N1}
Constraint: ris([X,Y]in _N1,[],true,X,true) = {}
```

stating that R cannot contain more than one pair whose first component is 1, which is incorrect.

Observe that most of the RIS that you will need can be defined with these patterns. So, in general, you will not need to check whether your patterns verify Definitions 5.1 and 5.2.

Furthermore, if your formula is not going to end up resolving a constraint such as:

```
ris(X in D, G(X), Q(X)) = {t / ris(Y in D, F(Y), P(Y))}
```

where D is a variable and t stands for any {log} term, then the condition on the pairwise co-injectivity of the patterns can be dropped. Note that D is the same variable used as RIS domain at both sides of the equation.

5.1.5 Enumerating the elements of a RIS

Given an equation of the form $S = \text{ris}(X \text{ in } D, [], F(X), P(X))$, where S and D are variables, the RIS is not evaluated and thus remains as it is. However, when the domain is a ground set (i.e., {}, or $\{t_1, \dots, t_n\}$ with t_1, \dots, t_n ground), or a ground interval, then it is possible to enumerate the elements of the RIS by means of the is operator, which forces the evaluation of its term. For example, when the following is executed:

```
Sqrs is ris(X in int(1,100),[Y],true,[X,Y],Y is X*X)
```

{log} returns:

```
Sqrs = {[1,1],[2,4],...,[100,10000]}
```

Note, however, that if $Y \text{ is } X*X$ is written as part of the filter:

```
Sqrs is ris(X in int(1,100),[Y],Y is X*X,[X,Y])
```

{log} first prints a series of warning messages and only after them it prints the correct answer. This means that the answer is not fully reliable (although in this case is correct).

If parameter Y is eliminated by introducing a control expression:

```
Sqrs is ris([X,Y] in D,[], X in int(1,100),[X,Y],Y is X*X)
```

the domain is a variable and thus {log} simply returns:

```
Sqrs = ris([X,Y] in D,[], X in int(1,100),[X,Y],Y is X*X)
```


5.1.6 Automated proofs

As with extensional sets and binary relations, $\{log\}$ can be used as an automated theorem prover for formulas involving RIS *provided the formula is safe*. Remember that a formula is safe if all RIS terms possibly occurring in it contain only safe patterns (i.e., they are bijective and pairwise co-injective) and, if they contain parameters, then they are safe parameters (i.e., they are used only as the result of functional predicates). For instance, $\{log\}$ can prove that:

$$\text{inters}(A,B,C) \ \& \ D = \text{ris}(X \text{ in } A, X \text{ in } B) \ \& \ C \text{ neq } D$$

is false which means that

$$A \cap B = \{x \mid x \in A \wedge x \in B\}$$

is a theorem.

5.2 General intensional set terms

$\{log\}$ provides also another way to express intensional sets, by means of general intensional set (GIS) terms.

GIS terms are terms of one of the following forms:

$$\begin{aligned} &\{X : (G)\} \\ &\{X : \text{exists}(V, G)\} \\ &\{X : \text{exists}([V_1, \dots, V_n], G)\} \end{aligned}$$

where: X is a variable; s is a term representing either a set or an interval $\text{int}(a,b)$; V, V_i are variables “local” to G ; and G is an arbitrary $\{log\}$ formula containing at least one occurrence of X .

Intuitively, the intensional set term denotes the set of all instances of X satisfying the formula G .

The following are two simple examples using GIS.

- $\text{powerset}(S, P)$ is true if P is the powerset of set S .

$$\begin{aligned} \text{powerset}(S, P) \text{ :-} \\ P = \{X : (\text{subset}(X, S))\}. \end{aligned}$$

Sample goal:

$$\begin{aligned} \{log\} \Rightarrow \text{powerset}(\{a, b\}, P). \\ P = \{\{\}, \{a\}, \{a, b\}, \{b\}\}. \end{aligned}$$

- $\text{cross_product}(A, B, CP)$ is true if CP is the Cartesian product of sets A and B .

$$\begin{aligned} \text{cross_product}(A, B, CP) \text{ :-} \\ CP = \{P : \text{exists}([X, Y], P = [X, Y] \ \& \ X \text{ in } A \ \& \ Y \text{ in } B)\}. \end{aligned}$$

Sample goal:

$$\begin{aligned} \{log\} \Rightarrow \text{cross_product}(\{a, b\}, \{1, 2\}, CP). \\ CP = \{[a, 1], [a, 2], [b, 1], [b, 2]\}. \end{aligned}$$

GIS can occur everywhere ordinary set terms are allowed. Moreover, they can be nested at any depth, i.e., the formula of a GIS term can contain other GIS terms.

Note that the control expression of a GIS can be only a single variable, whereas control expressions of RIS can be also compound terms. Apart from this, GIS are more general than RIS. Hence, from a logical point of view, RIS can be always replaced by the equivalent GIS. From an operational point of view, however, their behavior can be quite different.

In fact, internally, predicates containing RIS terms are dealt with as constraints, while predicates containing GIS terms are always replaced by new predicates whose definition (given in terms of automatically generated *{log}* clauses) implements the set grouping mechanism which allows to collect into an extensional set all values satisfying a given intensional definition.

As a consequence, when the intensional set term denotes an infinite set or even an unbounded set, the use of GIS may lead to possibly incorrect computations. For instance, given the goal of Section 5.1.6 written using GIS instead of RIS, i.e.:

$$\text{inters}(A,B,C) \ \& \ D = \{X : (X \text{ in } A \ \& \ X \text{ in } B)\} \ \& \ C \text{ neq } D$$

{log} is not able to find it is unsatisfiable (actually it generates wrong solutions).

6 Quantifiers

{log} provides a form of *restricted quantifiers* (RQ) where the quantified variable ranges over a *{log}* set. There are *Restricted Universal Quantifiers* (RUQ) and *Restricted Existential Quantifiers* (REQ). RUQ are supported through predicates `foreach` and `forall`, while REQ are supported through predicate `exists`. Furthermore, the current version of *{log}* provides also a form of general existential quantifiers.

6.1 foreach and exists

The main way to express RUQ and REQ in *{log}* is by means of the `foreach/2`, `foreach/4`, `exists/2` and `exists/4` predicates:

- `foreach(X in A,F)`

where *X* can be either a variable or a control expression (cf. Section 5.1.2), *A* is any *{log}* set admitted as RIS domain, and *F* is any *{log}* formula. The semantics of such a constraint is the expected:

$$\forall x : x \in A \Rightarrow F$$

That is, *F* is a formula true for every element of *A*.

- `foreach(X in A,[params],F,functional predicates)`

which behaves as `foreach/2` while allowing the introduction of parameters and functional predicates (cf. Section 5.1). Note that quantified variables of a RQ are meant to be local to the RQ.⁶ Same considerations as with RIS apply to the use of the `let` construct in RQ (see at the end of Sect. 5.1.1).

⁶In its current form *{log}* doesn't check whether or not local variables are used outside the RQ. It's the user's responsibility to avoid such name clashes which may make *{log}* to produce unexpected behaviors.

- `exists(X in A,F)`

where arguments are as in `foreach/2`. The semantics of such a constraint is the expected:

$$\exists x : x \in A \wedge F$$

- `exists(X in A,[params],F,functional predicates)`

which behaves as `exists/2` while allowing the introduction of parameters and functional predicates (cf. Section 5.1).

`{log}` provides also the negated versions of `foreach/2`, `foreach/4`, `exists/2` and `exists/4`, namely `nforeach` and `nexists`. In particular, note that the logical meaning of `nforeach(X in A, [], F, true)` is $\neg \forall x : x \in A \Rightarrow F$, i.e., $\exists x : x \in A \wedge \neg F$. Actually, `exists/2` is implemented in terms of `nforeach` as follows:

```
exists(X in A, F) :- nforeach(X in F, [], neg(F))
```

Note that, then, `exists` may not work well in all cases due to the presence of `neg`. The same holds for `exists/4`.

The following are two simple examples where RUQ are used to iterate over all elements of the given set:

- `print_elements(S)` prints all elements of the set `S`, one in each line.

```
print_elements(S) :-
    foreach(X in S, write(X) & nl).
```

- `all_pair(S)` is true if all elements of `S` are pairs (i.e., `all_pair(S) \Leftrightarrow rel(S)`).

```
all_pair(S) :-
    foreach(X in S, [X1,X2], X = [X1,X2], true).
```

Sample goal:

```
{log}=> all_pair([peter,ann],[tom,mary],[john,ann])).
true.
```

RQ can occur everywhere ordinary predicates are allowed. In particular, RUQ and REQ can be nested at any depth, i.e., the formula of a RUQ can be a RUQ itself and so on; and the formula of a REQ can be a REQ itself and so on. Decidability of formulas including RQ is described below. The following is a safe formula showing a nested RUQ:

```
foreach(X in S1,foreach(Y in S2, X neq Y))
```

which can be used to state that `S1` and `S2` are disjoint sets (i.e., `disj(S1,S2)` is true). As an example, executing the goal:

```
{log}=> S1={a,b} & S2={Z} &
    foreach(X in S1,foreach(Y in S2, X neq Y)).
```

returns the constraint:

```
Z neq a, Z neq b
```

while executing:

```
{log}=> S1={a/R} & S2={c} &
        foreach(X in S1,foreach(Y in S2, X neq Y)).
```

returns the constraint:

```
foreach(X in R,foreach(Y in {c},[],X neq Y,true)), set(R)
```

In order to simplify the introduction of nested RQ, *{log}* allows to write a list of constraints of the form *X in A in foreach* and *exists*. For example:

```
foreach([X1 in A1,...,Xn in An],...)
```

For instance, the nested RUQ shown above stating that S1 and S2 are disjoint sets can be written more compactly as follows:

```
foreach([X in S1,Y in S2],X neq Y)
```

Decidability of formulas including RQ. Let $\{\dots/A\}$ be the domain of a RQ where A is a variable. In this case we will say that A is the *domain variable* of the RQ⁷. The innermost formula of a RQ is called its *quantifier-free formula*. For instance, *X neq Y* is the quantifier-free formula of the nested RUQ encoding *disj* shown above. Formulas including *foreach* and *exists* are safe provided at least one of the following conditions is met (for technical details see [14]):

1. The formula contains only *exists* and the quantifier-free formula belongs to a decidable fragment.
2. The formula contains only *foreach*, the quantifier-free formula belongs to a decidable fragment, and none of the domain variables are used in the quantifier-free formula.
3. The formula contains *foreach* and *exists* but all the *foreach* occur *after* any *exists*. Here ‘after’ means that the only nested RQ are of the form:

```
exists([X1 in A1,...,Xn in An],
      foreach([Y1 in B1,...,Ym in Bm], formula)
)
```

where *formula* is a quantifier-free formula fitting in a decidable fragment, and the nested *foreach* verifies 2.

4. The formula contains *foreach* and *exists* but doesn’t belong to the above class (i.e., some *exists* occur after some *foreach*). In this case the condition for decidability is as follows: the quantifier-free formula must belong to a decidable fragment, no *exists* occurring *after* a *foreach* share the same domain variable, and no domain variable of a *foreach* is used in the quantifier-free formula. For instance, the following two formulas *do not* verify the above condition:

```
foreach(X in {W / A}, exists(Y in {V / A}, formula))
```

```
foreach(X in {H / A}, exists(Y in B, formula_1)) &
foreach(Z in B, exists(W in {Q / A},formula_2))
```

⁷Clearly, if the domain of a RQ is just a variable then this is the domain variable.

Note that in the first case there's an `exists` after a `foreach` sharing variable `A`. The second case is more complex because is harder to see that there's an `exists` after a `foreach` sharing variable `A` as they are in different RUQ. However these two RUQ are connected through domain variable `B`—see [14] from Example 5 to Theorem 3.

If these conditions aren't met then `{log}` will most likely run forever when is called on such a formula but it may not, depending on the quantifier-free formula inside the RQ.

6.2 forall

`{log}` provides also another way to express RUQ by means of the `forall` predicates:

```
forall(X in A, F)
forall(X in A, exists(V, F))
forall(X in A, exists([V_1, ..., V_n], F))
```

where `X` is a variable, `A` is any `{log}` set admitted as RIS domain, `F` is an arbitrary `{log}` formula, containing at least one occurrence of `X`, and `V`, `V_i` are variables “local” to `F`.

The meaning of

```
forall(X in A, exists([V_1, ..., V_n], F))
```

is the same as

```
foreach(X in A, [V_1, ..., V_n], F, true)
```

Hence, from a logical point of view, `forall` can be always be replaced by the equivalent `foreach` predicate. In this respect, `forall` is motivated mainly for compatibility with previous versions of `{log}`.

From an operational point of view, however, `forall` behaves differently from `foreach` whenever the set over which the control variable ranges is a variable or a set containing a variable set part. As an example, executing the goal:

```
{log}=> foreach(X in R, X in {a,b}).
```

simply returns the constraint:

```
subset(R, ris(X in R, [], X in S, X, true)), set(R), set(S)
```

(note that this constraint is trivially true for `R = {}`). On the other hand, executing the goal:

```
{log}=> forall(X in R, X in {a,b}).
```

explicitly generates all possible solutions:

```
R = {}
R = {a}
R = {a,b}
R = {b}
```

Actually, the `forall` predicates are not dealt with as constraints. Executing `forall(X in A, F)` always starts a computation that iteratively executes the goal `F` over all elements of the set `A`. If `A` and `F` are not enough instantiated this can lead to an infinite computation. For instance, executing the goal:

```
{log}=> forall(X in R,X in {a/S}) & a nin R.
```

after generating the first solution $R = \{\}$, will go into an infinite loop trying to add more and more elements to R which anyway contains a .

6.3 General existential quantifiers

`{log}` provides also a simple form of general existential quantifiers, where the quantified variable is not required to range over a specified domain:

```
exists(X,F)
```

where X is a (single) variable and F is any `{log}` formula.

This form of quantification can be used, for instance, to make explicit the otherwise implicit existential quantification of fresh variables in clause bodies, as well as of the so called parameters of RIS and RQ. As an example, predicates `singleton_set` and `not_singleton_set` defined in Sect. 3.5 can be equivalently defined as:

```
singleton_set(X) :- exists(Y,X = {Y}).
not_singleton_set(X) :- neg(exists(Y,X = {Y})).
```

In this case, by issuing the goal

```
{log}=> not_singleton_set({1}).
```

`{log}` recognizes it is using a form of negation that it can't handle, and so it tries to use `naf` in place of `neg`, printing the warning message: `using unsafe negation`. This means that the answer *might be incorrect*—although in this particular example it is correct.

As another example, the following formula

```
D = {[a,b],[1,1],[1,2]} & S is ris(Z in D,[X,Y],Z = [X,Y] & X neq Y).
```

using a RIS with two parameters X and Y , can be equivalently written without parameters but using nested existential quantifiers:

```
D = {[a,b],[1,1],[1,2]} &
S is ris(Z in D,[],exists(X,exists(Y,Z = [X,Y] & X neq Y))).
```

In both cases, the use of the existential variables X and Y inside the RIS is unsafe. In the second case, however, `{log}` tries to use `naf` in place of `neg`, printing the warning message concerning unsafe negation. Again, in this specific case, the use of `naf` allows the solver to obtain a correct answer (namely, $S = \{[1,2], [a,b]\}$).

It is worth noting that by using restricted existential quantifiers instead of the general ones we always get a reliable answer. For instance, the definition of `not_singleton_set` can be easily generalized by allowing the domain of Y to be an argument of the predicate, i.e.,

```
not_singleton_set(X,D) :- neg(exists(Y in D,X = {Y})).
```

In this case, even if both X and D are left unspecified, we still get a correct answer:

```
{log}=> not_singleton_set(S,R).
```

```
true
```

```
Constraint: set(R), foreach(_X in R,neg S={_X})
```

OPERATOR	$\{log\}$	MEANING
simple equality	$n \text{ is } e1$	$n = e_1$
less or equal	$e1 \leq e2$	$e_1 \leq e_2$
less	$e1 < e2$	$e_1 < e_2$
greater or equal	$e1 \geq e2$	$e_1 \geq e_2$
greater	$e1 > e2$	$e_1 > e_2$
equal	$e1 ::= e2$	$e_1 = e_2$
not equal	$e1 \neq e2$	$e_1 \neq e_2$

Table 6: Comparison arithmetic operators available in $\{log\}$

FUNCTION	$\{log\}$	MEANING
addition	$e1 + e1$	$e_1 + e_1$
subtraction	$e1 - e1$	$e_1 - e_2$
product	$e1 * e1$	$e_1 \times e_2$
division	$e1 / e1$	e_1 / e_2
integer division	$e1 \text{ div } e1$	$e_1 \text{ div } e_2$
integer module/remainder	$e1 \text{ mod } e2$	$e_1 \text{ mod } e_2$

Table 7: Arithmetic functions available in $\{log\}$

7 Solving formulas including integer numbers

$\{log\}$ deals with arithmetic expressions through a number of predefined predicates. The comparison arithmetic operators available in $\{log\}$ are shown in Table 6. In the table, $e1$ and $e2$ are arithmetic expressions, and n is either a variable or a numeric constant. An arithmetic expression is either a variable or a numeric constant or an arithmetic function (see Table 7) applied to its arguments, which are in turn arithmetic expressions. Numbers can be either integer or floating-point numbers.

For example, the following arithmetic formulas are solved as shown:

```
{log}=> X is 3*5.
X = 15
```

```
{log}=> 1.5 + 1 > 0.7.
yes
```

As Prolog, $\{log\}$ does not evaluate arithmetic expressions unless they occur as parameters in one of the predicates listed in Table 6. As an example, given the formula:

```
{log}=> 2 + 3 in {5}.
```

$\{log\}$ answers no because the expression $2 + 3$ is left unevaluated and $2 + 3$ does not belong to the set $\{5\}$. Conversely, using the `is` predicate, the formula:

```
{log}=> X is 2 + 3 & X in {5}.
```

turns out to be satisfiable and the answer will be $X = 5$. In fact, the `is` predicate forces `{log}` to evaluate the expression at the right-hand side as soon as possible.

If the expression `e_i` in the predicates of Table 6 is a floating-point expression, then all variables possibly occurring in `e_i` must have a constant value when they are evaluated, as in Prolog. Otherwise, a problem in the arithmetic expression is detected and `{log}` answers `no`. Arithmetic predicates containing real numbers are not dealt as constraints, but exactly as in Prolog. For example:

```
{log}=> 1.5 + X > 0.7 & X is 2*3.0.
Problem in arithmetic expression
no
```

while

```
{log}=> X is 2*3.0 & 1.5 + X > 0.7.
X = 6.0
```

yields the correct answer.

Conversely, if `e_i` is an integer expression, then it can contain uninitialized variables. As an example:

```
{log}=> 34 is X + 1.
X = 33
```

In fact, predefined arithmetic predicates over integer expressions are dealt with by a constraint solver. Specifically, one can use either a constraint solver over finite domains (namely, CLP(FD)) or a constraint solver over rationals (namely, CLP(Q)). By default, `{log}` starts solving arithmetic predicates by calling CLP(Q). Users can change this by issuing `int_solver(clpfd)` and can reset the default with `int_solver(clpq)`.

Both solvers have their advantages and disadvantages. We briefly analyze them in the next sections. See Section 7.3 for a few considerations on which solver should be used.

7.1 CLP(FD)

The CLP(FD) solver is *incomplete*. That is, given a goal G , if the answer is `no`, then G is surely unsatisfiable; otherwise, it is not guaranteed, in general, that G is satisfiable. For example:

```
{log}=> 34 > X + 1.
***WARNING***: non-finite domain
true
Constraint: X in int(inf,32)
```

`int(inf,32)` represents the integer interval $(-\infty, 32]$ (see next subsection). The warning message means that the answer *might be incorrect*—although in this particular example it is correct.

As another example:

	OPERATOR	$\{log\}$	MEANING
integer		<code>integer(t)</code>	t is an integer number
integer		<code>ninteger(t)</code>	t is not an integer number

Table 8: integer and ninteger constraints

```
{log}=> X + 1 > Y & X + 1 < Y.
***WARNING***: non-finite domain
true
Constraint: integer(X), integer(Y)
```

This goal is clearly unsatisfiable, but $\{log\}$ (actually the underlying CLP(FD) solver) is not able to detect it. `integer(X)` is a $\{log\}$ constraint that is true if and only if X is an integer number. There is also its negated version `ninteger` (see Table 8).

The solver becomes complete (i.e., a decision procedure) if we provide a finite domain for each integer variable which occur in the formula to be checked.

7.1.1 Finite domains

Domains for integer variables are specified through *integer intervals*. In mathematics an integer interval is noted $[m, n]$ and represents the set $\{i \in \mathbb{Z} \mid m \leq i \leq n\}$. In $\{log\}$ intervals are noted as `int(m,n)`, where m and n can be, in general, either integer constants or variables and represent the same than in mathematics (see Section 9). *Finite domains* are specified through ground intervals, i.e., intervals with constant limits.

Finite domains are associated to integer variables through membership constraints. The formula:

```
X in int(1,10)
```

states that the domain of the variable X is the interval $[1, 10]$.

The last two goals above, give the correct answers if we provide suitable domains for the integer variables X and Y .

```
{log}=> 34 > X + 1 & X in int(1,100).
X = 1
...
Another solution? (y/n)
X = 32
Another solution? (y/n)
no
```

```
{log}=> X + 1 > Y & X + 1 < Y &
      X in int(1,10) & Y in int(1,20).
no
```

(13)

7.1.2 Labeling

`{log}`, by default, always performs labeling at the end of the computation for all the integer variables which have a finite domain associated with them in the resulting final formula (provided CLP(FD) is the active integer solver). Labeling a variable X with domain D means non-deterministically assigning to X one by one all possible values in D . After each value has been assigned, then the whole constraint is analyzed again to check its satisfiability.

If one wants to suppress the default activation of labeling one can give the goal:

```
{log}=> nolabel.
```

If we, successively, give the goal

```
{log}=> 34 > X + 1 & X in int(1,100).
```

then the answer now will be

```
true
Constraint: X in int(1,32)
```

instead of generating all possible values for X as in the case when labeling is active.

When global labeling is deactivated we can nevertheless perform labeling on a single variable by using the built-in predicate `labeling(X)`.

Global labeling can be reactivated at any moment by issuing the goal:

```
{log}=> label.
```

The domain of an integer variable can be obtained also as the result of solving some arithmetic constraint on this variable. For example, the goal:

```
{log}=> 34 > X + 1 & X >= 1 & X <= 100.
```

will produce the same result as the goal `34 > X + 1 & X in int(1,100)` shown above.

Note that labeling is performed only for variables which have a bounded domain associated with them. For example,

```
{log}=> 34 > X + 1 & X <= 100.
***WARNING***: non-finite domain
true
Constraint: X in int(inf,32)
```

where it is evident that no labeling has been performed.

Observe that in goal (13) it is enough to specify the domain for one of the two variables; for example:

```
X+1 > Y & X+1 < Y & X in int(1,10).
```

will produce the same result as above.

Finally note that the predicate `X in {1,2,3}` is logically equivalent to `X in int(1,3)`, but its processing by the `{log}`'s solver is quite different. Actually, `X in {1,2,3}` is operationally equivalent to

```
X in int(1,3) & labeling(X).
```

Thus, `X in {1,2,3}` is not used to associate a domain to the variable X ; rather it is used to nondeterministically assign to X each value from a set of possible values.

7.2 CLP(Q)

The CLP(Q) solver is complete for *linear arithmetic* (be it real, rational or integer). In other words, it can give the right answer whenever the formula is linear, i.e., multiplication is restricted to expressions of the form $x*y$ where either x or y are constants, and division and remainder are restricted to constants.

`{log}` uses CLP(Q) restricted to integer solutions. Thus, for instance, the goal:

```
{log}=> X + 1 > Y & X + 1 < Y.
```

which has solutions over the rational numbers, is found to be unsatisfiable over the integers; hence, `{log}` answers no.

The CLP(Q) solver can be activated at any time by issuing `int_solver(clpq)`.

When CLP(Q) is the active integer solver, `{log}` does not perform automatic labeling as with CLP(FD). You can nevertheless perform labeling on a single variable by using the built-in predicate `labeling`. If X is constrained to range over a ground interval, then `labeling(X)` non-deterministically assign to X one by one all possible values in the interval; otherwise, i.e., the domain of X is unbounded, `labeling(X)` does nothing. For example, executing the goal

```
{log}=> 34 > X + 1 & X >= 1 & X <= 100.
```

will produce the answer

```
true
Constraint: 34>X+1, X>=1, X<=100, integer(X), ...
```

meaning that the input formula is satisfiable.⁸ If we conjoin `labeling(X)` to the input formula, then the answer will be:

```
X = 1
...
Another solution? (y/n)
X = 32
Another solution? (y/n)
no
```

i.e., the same result as with CLP(FD) using the default labeling.

div and mod in CLP(Q). Since `div` and `mod` are not available over CLP(Q), one can use Euclid's division lemma as a way to compute them. Then, say that we want to test a number for parity:

$$0 = x \bmod 2$$

In `{log}` over CLP(Q) the correct way is to find the quotient of $x/2$:

```
{log}=> X is 2*Q.
```

where Q is a new variable. As can be seen, this is a linear constraint and so CLP(Q) can always return the right answer.

⁸The constraints not shown in the computed answer are (negligible) integer constraints over fresh internal variables.

How `{log}` uses CLP(Q). `{log}` uses CLP(Q)'s `bb_inf/4` predicate to determine whether a conjunction of linear integer constraints is satisfiable over the integers. See the CLP(Q) documentation⁹ for further details.

Non-linear expressions in CLP(Q). If the formula passed to CLP(Q) contains non-linear expressions the returned answer is unreliable. `{log}` alerts the user with a proper warning message. For example:

```
{log}=> A is X*Y & B is Y*X & A neq B.

***WARNING***: non-linear expression over CLP(Q); possible unreliable answer

true
Constraint: A is X*Y, B is Y*X, A neq B
```

7.3 Which integer solver should be used?

As we have said, each integer solver has its own advantages and disadvantages. Hence, you should use CLP(FD) or CLP(Q) depending on how you are using `{log}`. In general, if you are using `{log}` as a programming language, then CLP(FD) should be your first choice. In this situation the solver mode should be preferred over the prover mode—cf. Section 11. Conversely, if you are using `{log}` as an automated theorem prover, then CLP(Q) is definitely the integer solver to be used—because it is complete for linear arithmetic thus turning no answers into real unsatisfiability proofs if linear arithmetic constraints are in the formula. Recall that if you are using `{log}` as an automated theorem prover then you should use it in prover mode.

8 Cardinality constraints

`size` is a set predicate that represents the cardinality of a set. `size`, and its negated version `nsiz`, are defined in Table 9.

The first argument of both predicates can be either a variable or a set term, including integer intervals and CP terms, but not RIS terms. The second argument can be either a variable or an integer constant. As an example, given the following goal:

```
{log}=> size({1/R},M).
```

we get as first answer:

```
true
Constraint: 1 nin R, size(R,_N1), _N1>=0, M>=1, _N1 is M-1,
           set(R)
```

If the second argument of `size` is a constant k and the first is a variable then the computed answer depends on the operation mode of the solver (cf. Sect. 11). In solver mode the most general set of k elements is explicitly shown. As an example, the answer to the following goal:

⁹https://www.swi-prolog.org/pldoc/doc_for?object=bb_inf/4

	OPERATOR	$\{log\}$	MEANING
set cardinality		<code>size(A,N)</code>	$ A = N$
not set cardinality		<code>nsize(A,N)</code>	$ A \neq N$

Table 9: The set cardinality operators

```
{log}=> size(A,3).
```

is

```
A = {X,Y,Z}
Constraint: X neq Y, X neq Z, Y neq Z
```

because $\{X,Y,Z\}$, with X , Y and Z variables, is the most general set of three elements provided they hold different values—and from here the constraint.

Conversely, if we are in prover mode, then the solver may check the satisfiability of the input formula without explicitly generating sets involved in size constraints of the form `size(A,k)`. For example, given the following goal:

```
{log}=> size(A,10) & subset({1,2,3},A).
```

we get as first answer:

```
A = {1,2,3/_N1}
Constraint: 1 nin _N1, size(_N1,7), 2 nin _N1, 3 nin _N1,
           set(_N1)
```

whereas in solver mode, A would be bound to $\{1,2,3, _N7, _N6, _N5, _N4, _N3, _N2, _N1\}$, along with the necessary constraints to ensure that elements in the set are all distinct from each other.¹⁰

Although the second argument of a size constraint can only be an integer constant or variable, users can link it to more complex (linear) expressions by means of the `is` or the ordering operators, as shown in the following examples:

```
{log}=> size(S,N) & N > 1.
{log}=> size({1/R},N) &
      N is 2*X + 3*Y + 4 & X > -6 & 2*Y + 5 < 10.
```

8.1 Decidable formulas involving cardinality constraints

$\{log\}$ provides a decision procedure for formulas involving size constraints provided the following conditions are met:

1. The only constraints in the formula are those of Tables 1, 6 and 8.

That is, no relational constraints are allowed in the formula.

¹⁰As a more practical solution, in the current version, if k is less or equal to a given threshold (now fixed at 6), then solving the constraint `size(A,k)` causes the set A to be anyway generated, disregarding the solver execution mode.

2. The first argument of any size constraint in the formula is either the empty set, a variable or an extensional set. This means that size will, in general, not work well when the first argument is a CP term, or a RIS term, or when the set part of the first argument is one of these.
3. All integer constraints in the formula are linear and CLP(Q) is the active integer solver.

For example, `{log}` is able to detect that the last two formulas given above are satisfiable. Similarly, `{log}` can detect that the formula:

```
{log}=> subset(A,B) & size(A,CA) & size(B,CB) & CA = CB &
        A neq B.
```

is unsatisfiable.

8.2 The solved form of formulas involving size constraints

Some solutions returned by `{log}` when the formula involves size constraints might be too abstract. For example the answer to the following formula:

```
{log}=> size(A,M) & 1 <= M & M <= 2 & size(B,N) & 5 <= N &
        subset(C,B) & size(C,K) & 7 <= K.
```

is

```
true
Constraint: size(A,M), M>=0, 1<=M, M<=2, size(B,N), N>=0,
           5<=N, subset(C,B), size(C,K), K>=0, 7<=K
```

that is, the formula itself. This means the formula is satisfiable and that all the possible solutions can be obtained by fixing values for the variables as long as all the constraints are met. However, this answer does not point out an evident concrete solution for the formula.

In general, when the size constraint is present in the answer, substituting all set variables by the empty set can lead to unsound solutions. Manually computing a concrete solution from such an answer can be cumbersome and error prone. Therefore, for these cases, `{log}` provides the `fix_size` and `nofix_size` built-in predicates. The latter is active by default. When `fix_size` is issued, the answer to the above goal is a more concrete solution:

```
A = {_N8},
M = 1,
B = {_N7,_N6,_N5,_N4,_N3,_N2,_N1},
N = 7,
C = {_N7,_N6,_N5,_N4,_N3,_N2,_N1},
K = 7
Constraint: _N7 neq _N6, _N7 neq _N5, _N7 neq _N4, _N7 neq _N3,
_N7 neq _N2, _N7 neq _N1, _N6 neq _N5, _N6 neq _N4, _N6 neq _N3,
_N6 neq _N2, _N6 neq _N1, _N5 neq _N4, _N5 neq _N3, _N5 neq _N2,
_N5 neq _N1, _N4 neq _N3, _N4 neq _N2, _N4 neq _N1, _N3 neq _N2,
_N3 neq _N1, _N2 neq _N1
```

goalsol (Section 3.2) produces even more concrete solutions also for formulas involving cardinality constraints. Recall to reactivate `nofix_size` if you are expecting abstract solutions.

If one wants simply to know which are the smallest cardinalities of the set variables occurring in size constraints as to satisfy the formula, without explicitly computing the relevant sets, then it is possible to use the `show_min` and `noshow_min` built-in predicates. As an example, by executing:

```
{log}=> show_min.
{log}=> size(A,M) & 1 <= M & M <= 2 & size(B,N) & 5 <= N &
        subset(C,B) & size(C,K) & 7 <= K.
```

we get

```
true
Constraint: M=1, N=7, K=7,
            size(A,M), M>=0, 1<=M, M<=2, size(B,N), N>=0, 5<=N,
            subset(C,B), size(C,K), K>=0, 7<=K, set(A), set(B),
            set(C)
```

where $M=1$, $N=7$, $K=7$ represent the smallest cardinalities of sets A , B and C that make the input formula true.

9 Finite integer intervals

`{log}` allows to represent *finite integer intervals* and to deal with them as sets of integer numbers.¹¹ The integer interval $[m, n]$ is written in `{log}` as `int(m,n)`; m and n , called limits, can be either variables or integer constants. If both interval limits are constants we say that `int(m,n)` is a *ground interval*, while if one of the limits is a variable it is a *variable interval*. Note that limits of variable intervals can participate in arithmetic constraints. For example:

```
{log}=> un({X,Y},{V,W},int(M,5)) & M is X - Y.
X = 4,
Y = 2,
V = 5,
W = 3,
M = 2
```

An interval `int(m,n)` where $m > n$ denotes the empty set.

9.1 Decidable formulas involving integer intervals

If the input formula fulfills the following conditions:

- only operators of Tables 1 and 9 are involved;
- only linear integer arithmetic is involved;
- CLP(Q) is the active integer solver,

¹¹From now on, we will say integer interval or just interval meaning finite integer intervals.

then $\{log\}$ will always compute the right answer even when set arguments are terms of the form $int(m,n)$ (i.e., $\{log\}$ provides a decision procedure for those formulas).

In this case:

- extensional sets and intervals can be freely combined, e.g. $un(\{X,Y\}, \{V,W\}, int(M,5));$
- intervals can also occur as the set part of extensional sets, e.g., $\{-1/int(1,N)\}.$

When operators other than those in Tables 1 and 9 are involved or when the formula contains non-linear integer arithmetic, the answer returned by $\{log\}$ is unreliable (i.e., $\{log\}$ is no longer guaranteed to provide a decision procedure for those formulas). It can be made reliable if the limits of all the intervals in the formula are constants (i.e., only ground intervals are involved). If this is the case, intervals can be safely used as the domain of a RIS, the domain of a RUQ and as arguments of the operators of Tables 3 and 5. Intervals cannot be the arguments of CP terms.

9.2 Defining set operators using intervals

Some powerful set operators can be defined using (variable) intervals and $\{log\}$ can automatically reason about them within the decidable fragment. These are gathered in the $\{log\}$ library `setloglibIntervals.slog`. Here we comment on one of them—see Sect. 10 for more.

Integer intervals can be used to define a predicate stating when an element of a set is the successor of another element of the same set.

```
ssucc(A,X,Y) :-
  X < Y &
  A = {X,Y/A1} & X nin A1 & Y nin A1 &
  un(Inf,Sup,A1) & disj(Inf,Sup) &
  M is X - 1 & subset(Inf,int(_,M)) &
  N is Y + 1 & subset(Sup,int(N,_)).
```

In this way, we can get the successor of a given element in a given set:

```
{log}=> ssucc({2,5,-1,9,0},5,M).
M = 9
Constraint: _N1=<2, _N1=< -1, _N1=<0
```

But also the predecessor:

```
{log}=> ssucc({2,5,-1,9,0},M,0).                                     [the second argument is a variable]
M = -1
Constraint: 2=<_N1, 5=<_N1, 9=<_N1
```

And we can prove properties true of `ssucc`:

```
{log}=> ssucc(S,X,Y) & Z in S & X < Z & Z < Y.
no
```

Note that some of the predicates listed in `setloglibIntervals.slog` can also be encoded with RIS and RUQ (cf. Sections 5.1 and 6). Which encoding is the best cannot be told because it depends on the context where they are used.

10 Aggregation functions

`{log}` provides some aggregation or aggregate functions¹² within its decision procedures, and some others can be defined outside of them.

10.1 Minimum and maximum of a set

`{log}` provides predicates `smin(S,min)` and `smax(S,max)` where `S` is a set and `min` and `max` can be integer constants or variables. These predicates are true when `min` (`max`) is the minimum (maximum) of set `S`. Both predicates are within the decidable fragments implemented in `{log}` as long as the second argument participates only in linear integer arithmetic (and the active integer solver is `CLP(Q)`).

The minimum of a set can be defined in terms of RUQ or in terms of integer intervals—same considerations apply to the maximum of a set. `smin` is defined in terms of RUQ.

```
smin(S,M) :- M in S & foreach(X in S, M =< X).
```

Then, we can compute the minimum of a given set:

```
{log}=> smin({2,5,-1,9,0},M).
M = -1
Constraint: 2=<_N1, 5=<_N1, -1=<_N1, 9=<_N1, 0=<_N1
```

```
{log}=> smin({2,X,-1,9,0},M).                                     [one element is a variable]
M = X
Constraint: X=<2, X=< -1, X=<9, X=<0
```

```
Another solution? (y/n)y
M = -1
Constraint: -1=<X
```

And we can prove properties true of `smin` as long as the formula remains in the decidable fragment:

```
{log}=> smin(S,M) & X in S & X < M.
no
```

The library `setloglibIntervals.slog` includes a predicate that computes the minimum of a set, called `setmin`, defined in terms of intervals:

```
setmin(S,M) :- M in S & subset(S,int(M,_)).
```

10.2 Sum of a set

The predicate `sum(Set,Sum)` computes the sum of a set. The first argument of `sum` can be either a variable or an extensional set or an integer interval with constant limits. The second argument can be either a variable or an integer constant. When bound, the first argument must denote

¹²Wikipedia.org: [Aggregate function](#)

either the empty set or a set of *non-negative* integer numbers. In particular, when applied to an empty set it returns 0.

Note that both elements of an extensional set and its set part can be uninitialized variables. For example, executing the goal¹³:

```
{log}=> sum({X1,X2},2) & labeling(X1)
```

we get the three solutions:

```
X1 = 0, X2 = 2
X1 = 2, X2 = 0
X1 = 2, X2 = 2
```

However, when both the first and the second arguments are variables occurring in some other constraints in the input formula, the solver may be unable to determine the satisfiability/unsatisfiability of the formula. For example, given the formula:

```
{log}=> sum(A,S1) & sum(A,S2) & S1 < S2.
true
Constraint: sum(A,S1), S1 >= 0, sum(A,S2), S2 >= 0, S2 > S1
```

the answer is clearly wrong.

In order to get the correct answer one should bound integer variables to ground intervals of the form $X \text{ in } \text{int}(m,n)$ for some constants m and n , and force labeling for at least some of them (remember that, if CLP(FD) is activated, then labeling is performed automatically at the end of the computation). For example, `{log}` gives the correct answer in the following case:

```
{log}=> int_solver(clpfd).
{log}=> sum(A,S1) & sum(A,S2) & S1 < S2 & S1 in int(1,10) & S2 in int(1,10).
no
```

Hence, in the current version, `{log}` does not provide a decision procedure for formulas involving `sum`. Removing this limitation is a goal for future releases. However, as a first step, consider the following section.

10.3 Sum of an array

The contents of this section and its implementation in `{log}` are still experimental

Arrays can be defined by the following `{log}` formula:

```
arr(A,N) :- 0 < N & pfun(A) & dom(A,int(1,N)).
```

That is, an array A of length N is a function whose domain is the interval $[1,N]$. For example:

```
{log}=> arr({[1,5],[2,3],[3,8],[4,2]},4).
yes
```

¹³Here we assume CLP(Q) is the active integer solver; if CLP(FD) is active, labeling is unnecessary as is performed automatically.

but also:

```
{log}=> arr(A,4).
A = {[1,_N4],[2,_N3],[3,_N2],[4,_N1]}
```

The decidability of arrays in $\{log\}$ has not been deeply studied, yet. However, as a rule of thumb, it is possible to say that $\{log\}$ formulas containing $arr/2$ belong to a decidable fragment if the cardinality of arrays, and anything related to them, is never taken. For example, the following is a formula laying *outside* that decidable fragment:

```
arr(A,N) & ran(A,R) & size(R,K) & K < N
```

because we are computing the cardinality of the range of array A. Taking the cardinality of some set containing some of the elements of an array will be useful in some circumstances. However, according to preliminary experiments, there are many non-trivial problems where taking the cardinality of some set related to an array isn't necessary. This implies that those problems belong to the decidable fragment.

Summing the elements of an array is one of those problems. Assuming A is an array of length at least K, the following predicate computes the sum of the first K elements of A.

```
arrsum(A,K,Sum) :-
  arr(Tr,K) &
  applyTo(A,1,X) &
  Tr = {[1,X],[K,Sum]} / Tr1 & [1,X] nin Tr1 & [K,S] nin Tr1 &
  foreach(I in int(2,K),[I1,Y,Z,Si],
    [I,Si] in Tr,
    I1 is I - 1 & applyTo(Tr,I1,Z) & applyTo(A,I,Y) & Si is Y + Z
  ).
```

As an example:

```
{log}=> arrsum([1,5],[2,3],[3,8],[4,2],2,S).
S = 8
```

The sum is performed by computing the partial sums in each component of Tr. In effect, the following is true of $arrsum(A,K,Sum)$:

```
Tr(1) = A(1)
Tr(2) = Tr(1) + A(2)
Tr(3) = Tr(2) + A(3)
.....
Tr(k) = Tr(k-1) + A(k)
```

In a sense, Tr records the state trace of the standard imperative algorithm computing the sum of an array. Consequently, $arrsum/3$ would be an abstract or logical representation of that algorithm.

As can be seen, $arrsum/3$ never takes the cardinality of anything related to an array. So, according to our first studies, $arrsum/3$ belongs to the decidable fragment.

11 Using $\{log\}$ as an automated theorem prover

As we have said in Sect. 3.6, proving unsatisfiability can be computationally very hard. $\{log\}$ may take an unpractical time in proving that a given formula is unsatisfiable. In this section we present several user commands and facilities that can significantly improve $\{log\}$'s efficiency when used as an automated theorem prover.

11.1 Alternative rewrite rules and execution options

$\{log\}$ is basically a rewrite system that applies a set of rewrite rules to the input formula until a fixpoint is reached. Users can slightly change the set of rewrite rules that $\{log\}$ will apply to the input formula by means of so-called *execution options*. Each execution option activates an *alternative rewrite rule* for a particular constraint while at the same time deactivates the corresponding default rewrite rule. These options are meant to improve $\{log\}$'s efficiency when used as an automated theorem prover—although it's hard to predict which option will have a positive or a negative influence in the proof of a *particular* theorem.

There are two *independent* ways of setting the execution options.

- Using the mode command (Sect. 3.7) as follows:

```
{log}=> mode(prover([opt1, ..., optn])).
```

with $0 \leq n$ and where each opt_i is listed in the first column of Table 10. `mode(prover)` is equivalent to `mode(prover([]))` meaning that no execution option is activated (which in turn implies that the default rewrite rules are applied). When $\{log\}$ is loaded, `mode(prover)` is automatically executed.

When execution options are activated in this way they influence all the goals executed directly from the $\{log\}$ environment.

- Using `prover_all_strategies/1` as follows:

```
{log}=> prover_all_strategies([mod, [opt1, ..., optn]]).
```

where *mod* can be the *modifiers* `all` or `all_single`, and opt_i are the same as above. This predicate can also be used to get the current set of active execution options by passing it a variable:

```
{log}=> prover_all_strategies(X).
```

```
X = [mod, [opt1, ..., optk]]
```

The default value of `prover_all_strategies/1` is `[all, dftlist]` where *dftlist* is the list of all options of Table 10.

When execution options are activated in this way they influence all the goals executed by means of the commands `t_solve/1`, `t_solve/3` and `p_t_solve/1`, which are explained below.

The *modifiers* `all` and `all_single` are explained in the next section.

As can be seen in Table 10, some of the execution options implement a rewrite rule in terms of RUQ. While this considerably speeds up the execution of many goals, it also tends to slow down many others and in general produces more complex solutions when the goal is satisfiable.

OPTION	AFFECTS	DESCRIPTION
subset_unify	equality	Implements set equality as a double set inclusion instead of implementing it by exploiting set unification. In this way, for example, $\{log\}$ generates two solutions instead of four for $\{X / A\} = \{Y / B\}$. In other words, subset_unify is closer to one of the standard proofs techniques when it comes to set equality because it assumes the existence of an element in one set and tries to prove that it belongs to the other set, and vice versa.
un_fe	union	Implements $un(A, B, C)$ in terms of RUQ (Sect. 6) when C is not a variable and A or B are variables. In this way $\{log\}$ produces two answers instead of six when solving $un(A, B, \{X/C\})$, with A and B variables. These two answers encode the standard proof of $x \in A \cup B$ by considering $x \in A$ and $x \in B$.
comp_fe	composition	Implements $comp(R, S, T)$ (Sect. 4) in terms of RUQ when T is not a variable and R and S are variables. In this way, for example, $comp(R, S, \{[1, a], [2, b], [3, c]\})$ quickly returns only one solution if comp_fe has been activated whereas under the default configuration it will take longer to return the first solution and even much longer to return other solutions.
oplus_fe	overriding	Implements $oplus(R, S, T)$ (Sect. 4) in terms of RUQ. The default rewrite rule for <i>oplus</i> is implemented in terms of <i>dom</i> , <i>dares</i> and <i>un</i> which in many cases requires a hard computation. When oplus_fe is active, for example, the proof of unsatisfiability of $oplus(\{X, Y, Z/R\}, S, T) \wedge noplus(\{X, Y, Z/R\}, S, T)$ takes about one second whereas the default rule takes a very long time.
ran_fe	range	Implements $ran(R, B)$ (Sect. 4) in terms of RUQ.
noirules	several	By default $\{log\}$ applies some optional inference rules while the goal is processed. noirules deactivates the application of these inference rules.
strategy(ordered)	disjunction	Changes the order in which atoms are processed. It has shown to impact proofs of the form $p \wedge (q \vee r) \wedge s$, with p, q, r, s atoms. With the default strategy, $\{log\}$ first rewrites p and s , say into t , and then solves $t \wedge q$ and $t \wedge r$. Instead, with strategy(ordered) the proof is first transformed into two subproofs $(p \wedge q \wedge s)$ and $(p \wedge r \wedge s)$ and then the atoms are rewritten in the order they appear.

Table 10: Execution options

As we have said, it's very hard to predict what execution options will have a positive influence when proving some theorem. Then, users should try out different combinations of execution options in the hope that one of them solves the goal in a reasonable time. Given Table 10, the current number of possible combinations is 128. However, since some rules have influence only on particular constraints, if the theorem to be proved doesn't include some such constraint then the corresponding option can be ignored. Yet the number of possible combinations could still be too high. Next section shows how to deal with this in a more automatic way.

See Section 15.1 to know how to activate execution options when `{log}` is called from Prolog.

Decidability with alternative rewrite rules. `{log}` preserves the same decidability results when one or more of the alternative rewrite rules are activated. In other words, the solver doesn't become "less" or "more" complete by activating one of the execution options of Table 10. There can be differences in the solutions provided by `{log}` and even in how it doesn't terminate, but when it terminates the set of solutions with or without execution options are equivalent. In a sense, calling `{log}` with different execution options is like calling different solvers whose completeness (or lack of it) is the same, although their execution speeds tend to be different.

Concerning the differences in non-termination when `{log}` is called with different execution options consider the following example.

```
{log}=> dom(R,A) & ran(R,{X/A}).    % default config., blocks immediately

{log}=> mode(prover([subset_unify])).
{log}=> dom(R,A) & ran(R,{X/A}).    % infinite number of solutions

R = {[X,X]/_N2},
A = {X/_N1}
Constraint: dom(_N2,_N1), set(_N1), X nin _N5, comp(_N4,{[X,X]},_N4),...
```

Hence, in the default mode one can't tell whether or not this particular formula is satisfiable, whereas when `subset_unify` is active `{log}` finds it satisfiable but it's impossible to get a finite representation of all its solutions. This last point is crucial when this formula is part of a larger, unsatisfiable one because `{log}`, in general, won't be able to prove that.

11.2 Parallel execution

The command `p_t_solve(G)` solves `G` by running `G` in parallel in multiple (operating system) threads. Each thread runs `G` with some combination of the execution options listed in `prover_all_strategies`. The number of threads and the combinations of execution options in use depend on the current value of `prover_all_strategies` as follows:

- `[all,list]`: all the possible combinations of the elements of `list` are used in an equal number of threads. More precisely: `{log}` computes the powerset of `list`, creates a thread for each element of the powerset, activates the corresponding options and runs `G` in each thread.

For example, considering the default value of `prover_all_strategies`, `p_t_solve(G)` will create 128 threads that will run `G` in parallel, each with a different set of execution options activated.

- `[all_single, list]: {log}` creates a thread for each element of *list*, activates the corresponding option and runs *G* in each thread.

For instance, if the current value is `[all_single, [un_fe, comp_fe, oplus_fe, ran_fe]]`, `p_t_solve(G)` will create 4 threads that will run *G* in parallel, each with a different execution option (among `[un_fe, comp_fe, oplus_fe, ran_fe]`) activated.

As soon as one thread terminates the whole computation terminates as well¹⁴. In this way, the net execution time will tend to be the time needed by the thread running the best combination of execution options for that proof. Note that, however, if the machine has less cores than the number of threads, thread scheduling will increase the time needed also by the fastest one. Hence, either run your goal on a machine with enough cores, or reduce the number of execution options in `prover_all_strategies` as explained in the previous section, or wait longer.

Besides, `p_t_solve(G)` executes *G* for at most 1 minute¹⁵. This parameter can be changed with the following command:

```
{log}=> timeout(number).
```

where *number* can be a positive integer number representing an amount measured in milliseconds; or a variable, if the user wants to consult the current timeout. If `{log}` is unable to solve the goal before the timeout is met, the answer returned by `p_t_solve` will be `timeout`.

The following examples illustrates different behaviors on an eight cores standard laptop.

```
{log}=> prover_all_strategies(X).
      X = [all, [subset_unify, comp_fe, un_fe, oplus_fe, ran_fe, noirules,
                strategy(ordered)]]
{log}=> timeout(2000).
{log}=> p_t_solve(oplus({X,Y,Z/R},S,T) & noplus({X,Y,Z/R},S,T)).

timeout
```

`{log}` is unable to solve the goal in less than two seconds when the default value of `prover_all_strategies` is considered, in spite that there's at least one combination of execution options that would solve the goal faster. This is because the operating system has to schedule 128 threads using 8 cores making the "good" threads to use the computer as much as the "bad" ones. Now we set three execution options, with `oplus_fe` among them, which amounts to eight possible combinations (i.e., the number of available cores). In this way the goal is solved in less than 1.5 seconds.

```
{log}=> prover_all_strategies([all, [oplus_fe, subset_unify, un_fe]]).
{log}=> timeout(1500).
{log}=> p_t_solve(oplus({X,Y,Z/R},S,T) & noplus({X,Y,Z/R},S,T)).

no
```

¹⁴`{log}` uses SWI Prolog's [first_solution/3](#) to implement parallel execution.

¹⁵For this reason, `p_t_solve` stands for *parallel, timed solve*.

That is, now the operating system has to schedule just eight threads, plus other operating system processes, using eight cores. In this way our threads will be able to use the computer more time, than in the previous experiment, allowing one of them to solve the goal faster. Finally, we run the same goal with the `all_single` modifier with a one second timeout:

```
{log}=> prover_all_strategies([all_single,[oplus_fe,subset_unify,un_fe]]).
{log}=> timeout(1000).
{log}=> p_t_solve(oplus({X,Y,Z/R},S,T) & noplus({X,Y,Z/R},S,T)).

no
```

Hence, by using less threads they probably can use the computer for as long as they need, allowing `{log}` to solve the goal even faster. But in this case the user needs to analyze what options are likely to speed up the proof.

Extreme parallelism and timeouts. When a goal is run in parallel using many more threads than the number of available cores, threads might miss timeout signals. As a consequence, threads will run beyond the expected timeout. This is usually the case when `p_t_solve` is called when a “high” number of execution options belong to `prover_all_strategies`. As this number goes down, threads tend to miss less timeout signals. Clearly, this number is high or not in relation to the number of available cores. Note that the number of threads created by `p_t_solve` grows exponentially w.r.t. the number of executions options in `prover_all_strategies` when the `all` modifier is used, but grows linearly when `all_single` is used. The fact that threads tend to miss timeout signals under these conditions, is outside of the control of `{log}`.

What if the goal is satisfiable? Parallel execution in `{log}` is meant to be used to prove unsatisfiability. However, users might not know in advance whether or not the goal is unsatisfiable. In case the goal is satisfiable, `{log}` will return a first solution as in the normal case but it won’t be able to compute more solutions. Parallel execution in `{log}` cannot deal with non-determinism¹⁶. Hence, you will know the goal is satisfiable but you won’t be able to call for more than one solution.

11.3 Other user commands

There are two more user commands that can be exploited when using `{log}` as a theorem prover.

- `t_solve(G)` executes `G` for as long as the current timeout—i.e, the only difference with the normal interactive execution is the timeout.
- `t_solve(G,timeout,exec_conf)` executes `G` for as long as `timeout` and using the configuration given by `exec_conf`. Possible values for `exec_conf` are:
 - The empty list. Behaves as setting the current timeout to `timeout` and then calling `t_solve(G)`.
 - A list whose elements are the execution options listed in Table 10 and Appendix A. The execution options passed in the list are activated during the execution of `G`.

¹⁶This is a consequence of the same limitation of SWI Prolog’s `first_solution/3`.

- `try([optList1, ..., optListn])`, where each `optListi` is a list of execution options as in the previous item. `G` is first executed with `optList1`: if the execution doesn't timeout, no more is done and `t_solve` terminates, with either success or failure; if the execution timeouts, `G` is executed with `optList2`. This process continues until all the elements of the list are attempted. For more information see `setlog/5` with option `try` in Sect. 15.1.
- `tryp([optList1, ..., optListn])`, where each `optListi` is a list of execution options as in `try`. `{log}` creates a (operating system) thread for each element of the list. Each of these threads is configured with the corresponding `optList` and tries to solve `G`. As soon as one thread terminates, the whole computation is brought to an end. All threads are terminated as soon as `timeout` is reached. Since the goal is executed in parallel, only one solution will be returned if the goal is satisfiable.
- `try(prover_all)`. The powerset of the current value of `prover_all_strategies` is computed in list `power_set` and the call `t_solve(G, timeout, try(power_set))` is executed.
- `try(prover_all_single)`. Let `[opt1, ..., optn]` be the current value of `prover_all_strategies`, then the call `t_solve(G, timeout, try([opt1], ..., [optn]))` is executed.
- `tryp(prover_all)`. The powerset of the current value of `prover_all_strategies` is computed in list `power_set` and the call `t_solve(G, timeout, tryp(power_set))` is executed.
- `tryp(prover_all_single)`. Let `[opt1, ..., optn]` be the current value of `prover_all_strategies`, then the call `t_solve(G, timeout, tryp([opt1], ..., [optn]))` is executed.

Although, `try` and `tryp` may look similar, they aren't. `{log}` will return only one solution under `tryp` if the goal is satisfiable, but it will have a normal behavior under `try` if one execution attempt doesn't timeout. `try` is purely sequential; in this sense, it's like executing all the threads of `tryp` one after the other.

12 Types in `{log}`

As we have said, `{log}` accepts untyped formulas. For example, the following is a possible value for a `{log}` set:

```
{a, 1, {2}, [5, "messi"]}
```

It is also possible to operate with those sets:

```
{log}=> un({a, 1, {2}, [5, "messi"]}, {X}, {Y/R}).
Y = a,
R = {1, {2}, [5, "messi"], X}
Constraint: X neq a
```

As in Prolog, variables are not declared and can assume values of any type. `{log}` is able to distinguish between variables representing sets and variables representing non-set objects, in particular integer numbers. This distinction is made according to the constraints where a variable participates in. For instance:

```
{log}=> X > Y.
```

makes $\{log\}$ to classify X and Y as integer variables. This means that:

```
{log}=> X > Y & un(X,{1,2,3},Z).
```

will fail just because X cannot be an integer and a set at the same time.

In general the lack of types works well but it allows $\{log\}$ to accept formulas that cause undesired behaviors in some cases. For example:

```
{log}=> id({X/A},R) & id(R,A).
```

makes $\{log\}$ to enter an infinite loop that the user can interrupt by typing Ctrl+c. Due to the first constraint, $[X,X]$ belongs to R and by the second constraint $[[X,X],[X,X]]$ belongs to A which initiates the loop again. Internally, $\{log\}$ builds an increasingly larger ordered pair which eventually will consume all the available memory.

In a sense, this problem is caused because the formula is ill-typed. In effect, in a way, the first constraint states that A is a set of some elements and R is the identity function on A ; but the second constraint states quite the opposite: A is the identity function on R . A type system would deem this formula ill-typed and would reject it before any attempt on deciding its satisfiability is made.

Besides, types can help programmers in avoiding certain errors as is acknowledged by the programming languages community. On the other hand, types can complicate programs and formulas by imposing strong restrictions on some operations.

In an attempt to resolve this tension between type safety and *typeless* freedom, $\{log\}$ accepts untyped formulas but the user can activate a typechecker at will. If the typechecker is active all variables in formulas and clauses must be declared to be of a certain type and the typechecker is called before a formula is executed (in interactive mode) or when a file is consulted. The typechecker is activated by issuing:

```
{log}=> type_check.
```

and is deactivated with:

```
{log}=> notype_check.
```

Before going into the details of $\{log\}$'s type system, we present the typed version of the formula based on the id constraint analyzed above:

```
{log}=> id({X/A},R) & id(R,A) &
        dec(X,t) & dec(A,set(t)) & dec(R,set([t,t])).
```

Each dec constraint states that a variable is of a certain type. For instance, $dec(R,set([t,t]))$ states that R is a set of ordered pairs whose components are both of type t . If this formula is run while the typechecker is *not* active, $\{log\}$ will simply ignore the dec constraints. This would cause a loop, as explained above. Instead, if the typechecker is active, $\{log\}$ will report a type error and it will not execute the formula:

```

type error: in id(R,A)
             R is of type set([t,t])
             A is of type set(t)

```

The error comes from the fact that the type of `id` is expected to be:

```
id(set(T),set([T,T]))
```

for some type `T`. The error clearly informs that such a type can't be found given the types of the arguments.

Typing formulas is good but complicates some formulas such as the first one seen in this section:

```
{log}=> un({a,1,{2}},{5,"messi"}},{X},{Y/R}).
```

However, `{log}` provides a type system where an encoding of the set `{a,1,{2}},{5,"messi"}` can be correctly typed—see “Towards untyped sets” in Section 12.1.7.

In the following section the type system and other related features are introduced. In Section 13 the reader will find a complete example of a typed `{log}` program.

12.1 The type system

`{log}` defines a type system based on those enforced by the `Z` and `B` notations. In this sense, the type system is oriented towards a typed set theory.

As we have said, when the typechecker is active *all* variables must be declared to have *exactly one* type. These declarations are made by means of the `dec/2` constraint, called *type constraint*. In `dec(V,t)`, `V` must be a variable and `t` must be a type—as defined right afterwards. Type constraints can be anywhere in the formula—that is, it is not necessary to declare the type of a variable before its first use. There is available also a `dec` constraint whose first argument is a list of variables:

$$\text{dec}([V_1, \dots, V_n], t) \Leftrightarrow \text{dec}(V_1, t) \wedge \dots \wedge \text{dec}(V_n, t)$$

which helps in reducing the size of typed formulas.

In `{log}` types are not sets. That is, if `t` is a type one cannot write `X in t`. This is simply an ill-formed, incorrectly sorted constraint. `{log}` will fail immediately if such constraint is provided.

In `{log}` type identifiers and type constructors begin with a lowercase letter. The types and type constructors available in `{log}` are the following.

12.1.1 Integers

`int` is a type representing the set of integer numbers (\mathbb{Z}). Then a formula such as `X > Y` can be typed as follows:

```
{log}=> dec(X,int) & X > Y & dec(Y,int).
```

Numbers are automatically typed as expected. Then a formula such as `X > 10` can be typed as follows:

```
{log}=> dec(X,int) & X > 10.
```

`int` is a reserved word of the language when in type-checking mode. It can only be used where a type is allowed.

12.1.2 Character strings

`str` is a type representing the set of character strings. There are no special purpose operators defined over `str` in `{log}` so strings can be used mainly as elements of sets, as components of ordered pairs, etc. That is, for instance, the following are all type-correct:

```
{log}=> dec(X,str) & X = "Messi".
{log}=> "Pele" nin {"Messi","Maradona","Di Stefano"}.
{log}=> ["Di Stefano","Argentina"] = ["Maradona","Argentina"].
```

Atoms are not strings:

```
{log}=> dec(X,str) & X = messi.
type error: 'messi' doesn't fit in the sum type
{log}=> "messi" = messi.
type error: 'messi' doesn't fit in the sum type
```

`str` is a reserved word of the language when in type-checking mode. It can only be used where a type is allowed.

12.1.3 Basic types

Any *atom* can be used as a type. All these types are called *basic types*.

For example:

```
dec(A,address)
dec(N,name)
dec(Zip,zipcode)
dec(C,country)
dec(H,city)
```

are all possible type constraints declaring variables of basic types. Then, we have the following:

```
{log}=> dec(A,address) & dec(N,name) & A neq N.
type error: in A neq N
           A is of type address
           N is of type name
```

In some notations (e.g., `Z`) the structure or form of the elements of basic types is unknown. This provides an abstraction mechanism. For instance, the programmer do not want to say, at the moment, whether or not an address is a character string, or a number (house) and a character string (street). But (s)he wants to be able to distinguish between address'es and name's, so (s)he uses two different basic types.

In `{log}`, because is a programming language, basic types are associated to a known set of elements. If `t` is a basic type, then all its elements are of the form `t:⟨atom⟩`, for any atom. For example, if we want to bind the atom `john` to variable `N` of type `name`, then:

```
{log}=> dec(N,name) & N = john.
***ERROR***: type error: 'john' doesn't fit in the sum type
```

while

```
{log}=> dec(N,name) & N = name:john.
N = name:john
```

and

```
{log}=> dec(N,name) & N = city:john.
***ERROR***: type error: in N=city:john
N is of type name
city:john is of type city
```

The following are further examples of how the `:/2` operator works:

```
{log}=> t:A = u:a.
type error: t:A isn't well defined
{log}=> t:a = u:a.
type error: in t:a=u:a
t:a is of type t
u:a is of type u
{log}=> t:a = t:a.
yes [type correct, satisfiable]
{log}=> t:a = t:b.
no [type correct, unsatisfiable]
{log}=> {t:a,t:b} = {t:b,t:a,t:b}.
yes
```

In type-checking mode `:/2` is a reserved symbol. It can only be used as described in this section. See Section 12.9 to learn more about admissible terms in type-checking mode.

Basic types vs. strings (str). Note that replacing basic types with `str` might cause some problems. Using `str` instead of basic types is fine as long as you are aware that you are using the same type for things that might be quite different. For example¹⁷:

```
{log}=> iddef_type(city,str).
{log}=> iddef_type(name,str).
```

make `city` and `name` the same type, `str`. This might be confusing:

```
{log}=> dec(N,name) & dec(C,city) & N = "Leo" & C = "Leo".
N = Leo,
C = Leo
```

¹⁷`iddef_type` is explained in Section 12.2.

That is "Leo" can be a name and a city. This is not the case if city and name are basic types.

```
{log}=> city:'Leo' = name:'Leo'.
type error: in city:'Leo' = name:'Leo'
           city:'Leo' is of type city
           name:'Leo' is of type name
```

12.1.4 Enumerated types

`enum([e_1, \dots, e_n])` is an *enumerated type* whose elements are all the e_i .

For example:

```
enum([red,blue,green])
enum([normal,warning,failure,stop])
enum([messi,maradona,destefano,carlovich])
```

are all enumerated types. So a declaration such as:

```
dec(A,enum([red,blue,green]))
```

will constrain A to be bound to only those three values. Hence, for instance:

```
{log}=> dec(Color,enum([red,blue,green])) & Color = blue.
Color = blue
```

while by issuing

```
{log}=> dec(Color,enum([red,blue,green])) & Color = yellow.
```

we get a type error.

In an enumerated type, each e_i must be an atom, different from all the basic types in scope and from all other atoms declared in other enumerated types, even if occurring in different goals or different clause bodies—and from `int` and `str` which can only be used where a type can be used. All e_i in the list must be different from each other. The list must contain at least two elements. In this sense, enumerated types are *persistent* and have a *global validity*. The `reset_types` command can be used to delete all type declarations currently in use (see Section 12.10) thus removing all the enumerated types being used.

Note that `enum([yes,no])` is a different type than `enum([no,yes])`. Actually, the type-checker will issue a type error when the second type is used for the first time because 'no' is an element of another enumerated type.

See Section 12.2 to learn how to give a name to enumerated types so you do not have to repeat the enumeration in each type constraint.

12.1.5 Sum types

Enumerated types are a particular class of *sum types*. Sum types implement the widely known notion of *variant*¹⁸ (heavily used in functional programming languages).

For example, the following are all sum types:

¹⁸Wikipedia.org: [Tagged union](#)

```

sum([nil, some(str)])
sum([null, num(int), pair([int, int])])
sum([null, num(int), pair(int, int)])
sum([col(enum([red, blue, green])), other(sum([nil, some(str)]) )])

```

In the first case the type is composed of the values `nil` and any value of the form `some(s)` where `s` is of type `str`. The second type is composed of the values `null`, all the values of the form `num(i)` where `i` is of type `int`, and all the values of the form `pair([i, j])` where `i` and `j` are of type `int` and `[i, j]` is of a product type—see Section 12.1.6. The third type is isomorphic to the second one. The following is a possible goal using the second sum type:

```

{log}=> dec(X, sum([null, num(int), pair([int, int])])) & X = pair([1, 2]).
X = pair([1, 2])

```

A sum type is given by a list of terms of any arity. The arguments of non-nullary terms must be types. The head symbol of each of these terms is called *constructor*. So, for instance, `nil` and `some` are constructors. This emphasizes the fact that elements of a sum type are built or constructed according to the constructors that define the type.

Internally, the enumerated type `enum([e1, ..., en])` is rewritten as `sum([e1, ..., en])`. Then, enumerations are no more than sum types whose constructors are all nullary terms. For this reason, for now on, whenever we mention a sum type it includes also the case of an enumeration.

In a sum type, each constructor must be an atom, different from all the basic types in scope and from all other atoms declared in other sum types—and from `int` and `str` which can only be used where a type can be used. All constructors in the list must be different from each other. The list must contain at least two elements. Like enumerations, sum types have a global validity, which persists between one goal and another (in interactive mode) and between one loaded program and another. One can use the `reset_types` command to delete all type declarations currently in use—see Section 12.10.

These restrictions imply that if you want to introduce, for example, two or more *option types*¹⁹ you must use different constructors. In other words you can't use `none` and `some` for all the option types. For example:

```

dec(X, sum([nil, some(str)])) & dec(Y, sum([nil, some(int)]))

```

produces the following type error:

```

type error: in dec(Y, sum([nil, some(int)]))
type sum([nil, some(int)]) is not well-defined

```

because `nil` is part of two different sum types. In this case the correct declarations would be:

```

dec(X, sum([nils, somes(str)])) & dec(Y, sum([nili, somei(int)]))

```

This generalizes to more complex sum types.

¹⁹Wikipedia.org: [Option type](#)

12.1.6 Product types

If t and u are two types then $[t, u]$ is a type interpreted as the Cartesian product between t and u . This means that the elements of $[t, u]$ are ordered pairs whose first component is of type t and the second is of type u .

For example:

```
dec(B, [city, enum([red, blue, green])])
```

forces B to be bound only to ordered pairs whose first component is of type `city` and the second is `red`, `blue` or `green`. In this way:

```
B = [A, blue]
```

will type-check if `dec(A, city)` is in context. Conversely,

```
B is X + 7
```

will fail because `is` is of type `is(int, int)`.

Product types can be generalized to any number of products and can be nested at any level:

```
[t, str, [int, v]]
```

12.1.7 Set types

If t is a type then `set(t)` is a type representing all the sets whose elements are of type t . In other words, `set(t)` represents the powerset of t . Hence, if X is of type `set(t)`, then X is a set whose elements are of type t .

Obviously, set types are everywhere in $\{log\}$. Most of the set constraints available in $\{log\}$ are typed by means of the set type constructor. For example, the following is the type of the `un` constraint:

```
un(set(T), set(T), set(T))
```

for any type T . In other words, `un` is a polymorphic operator accepting sets of any type as long as all its elements are of the same type. The empty set is a polymorphic set term. Hence, $A = \{\}$ is a correctly typed formula provided A has been declared to be of a set type.

The extensional set constructor is typed in such a way as to accept elements of the same type. Then, a set such as $\{e_1, \dots, e_n/S\}$ is correctly typed if and only if every e_i is of type T and S is of type `set(T)`, for some type T .

Encoding untyped sets. The combination between the set and `sum` types allows to encode untyped sets. For example, the set used in the introduction to this section:

```
{a, 1, {2}, [5, "messi"]}
```

can be casted in terms of a set type combined with a `sum` type:

```
dec(S, set(sum([a, n(int), s(set(int)), p(int, str)]))) &
S = {a, n(1), s({2}), p(5, "messi")}
```


12.1.8 Types for binary relations and partial functions

By combining a product type and a set type it is possible to construct types representing binary relations. Typically:

```
set([t,u])
```

corresponds to the type of all binary relations whose ordered pairs have a first component of type t and a second component of type u . Since this type is frequently used in $\{log\}$, the `rel` type constructor is introduced as a synonym of a type based on a set and a product type:

```
rel(t,u) == set([t,u])
```

Precisely, all the relational operators available in $\{log\}$ have types based on `rel`. For example the following is the type of the `comp` constraint:

```
comp(rel(T,U),rel(U,V),rel(T,V))
```

for any types T, U and V . Again, `comp` is a polymorphic operator.

The differences between `rel(R)` (cf. Table 3) and `dec(R,rel(t,u))` are the following:

1. `rel` is part of $\{log\}$'s inference engine; `dec(R,rel(t,u))` is used only by the typechecker when it is active.
2. `rel(R)` is automatically added by $\{log\}$ in certain situations. For example, if you assert `id(A,R)`, $\{log\}$ automatically adds `rel(R)`. Only the user can assert `dec(R,rel(t,u))`.
3. `rel(R)` forces the elements of R to be ordered pairs but it does not state what the type of those pairs is. Then, if only `rel(R)` is asserted, $\{[1,a], [\{t\}, [x,1]]\}$ is a possible value for R .

Instead, if `dec(R,rel(t,u))`, for any types t and u , is asserted, then $R = \{[1,a], [\{t\}, [x,1]]\}$ will not type-check and the formula containing it will not be executed.

4. In this sense `rel(R)` is weaker than `dec(R,rel(t,u))`, but it's automatic.

Note that a `cp` term is a set of ordered pairs. Then the type of `cp(A,B)` is `rel(u,t)` if and only if A is of type `set(t)` and B is of type `set(u)`.

Observe that there is no type for partial functions. Then, if F is meant to be a partial function taking values from some type t and returning values of some type u , you have to assert the following:

```
{log}=> dec(F,rel(t,u)) & pfun(F) & ...
```

Furthermore, `pfun(F)` is usually a consequence or a property of a program and so you can use $\{log\}$ to automatically prove that this is actually the case. For example in:

```
{log}=> dec([F,G],rel(t,u)) & dec(D,set(t)) &
        dec(X,t) & dec(Y,u) &
        pfun(F) & dom(F,D) & X nin D & G = {[X,Y] / F}.
```

`pfun(G)` is a consequence of that formula. Then, you do not need to assert it, instead you can prove it:

```
{log}=> dec([F,G],rel(t,u)) & dec(D,set(t)) &
        dec(X,t) & dec(Y,u) &
        pfun(F) & dom(F,D) & X nin D & G = {[X,Y] / F} &
        npfun(G).
no
```

In this way, the formula is lighter but as stronger as if you were conjoined `pfun(G)` to it.

12.2 Type declarations

Sometimes a type is defined by means of a long, complex type expression. For example, the following type is taken from a `{log}` program implementing the Bell-LaPadula security model [13]:

```
rel(obj,[int,set(cat)])
```

Then, if you have to declare a couple of variables of that type the `dec` constraint becomes annoying:

```
dec([01,02],rel(obj,[int,set(cat)]))
```

For these situations `{log}` offers the `idef_type/2` and `def_type/2` commands. The first one is used in goals (in interactive mode), whereas the second is used in program clauses. For example:

```
{log}=> idef_type(t,rel(obj,[int,set(cat)])) .
{log}=> dec([01,02],t) & ...
```

That is, `def_type(t,expr)` and `idef_type(t,expr)` state that `t`, an atom, is a name for type `expr`. The effect of these commands is global and persistent. Afterwards it holds that:

```
dec(V,t) ⇔ dec(V,expr)
```

In `[i]def_type(t,expr)`: `t` cannot occur in `expr`; cannot be an element of a sum type (in scope); cannot be the first argument of another `def_type` command; and cannot be `int` or `str`. In turn, `expr` cannot be an atom—because in this case you would be giving a basic type another name. However, `t` *can* be used in other type definitions. For example, `ac` is used to define `oac` and `sac`:

```
{log}=> idef_type(ac,[int,set(cat)]).
{log}=> idef_type(oac,set([obj,ac])).
{log}=> idef_type(sac,set([sub,ac])).
{log}=> idef(A,ac) & dec(F,oac) & comp(F,{[A,A]},{}).
```

Naming sum types is another convenient use of the `[i]def_type` commands:

```
{log}=> idef_type(thebest,
                enum([messi,maradona,distefano,carlovich])).
{log}=> dec([P1,P2],thebest) & P1 neq P2.
```

See Section 12.10 to learn how type declarations can be consulted and managed.

12.3 Typing RUQ and REQ

RUQ and REQ (Section 6) are typed as any other constraint in $\{log\}$ with the exception that bound variables need not be typed—although they can be typed if users wish to do so. For example, the following is type correct, in spite that there's no type declaration for X :

```
dec(A,set(int)) & foreach(X in A, X > 0)
```

$\{log\}$ will infer X 's type from A 's. However, X can be explicitly typed as follows:

```
dec(A,set(int)) & foreach(X in A, dec(X,int) & X > 0)
```

Nevertheless, if the explicit type isn't the correct one, $\{log\}$ will issue a type error message:

```
{log}=> dec(A,set(int)) & foreach(X in A, dec(X,t) & X > 0).
```

```
***ERROR***: type error: in dec(X,t), variable X is already declared
```

In effect, when $\{log\}$ processes the RUQ it attempts to find out the type for X (which is int , given A 's type), but when it processes the inner formula the type inferred by $\{log\}$ for X doesn't coincide with the type declared by the user.

Same considerations apply when a control expression is used:

```
dec(A,set([int,t])) & foreach([X,Y] in A, X > 0)
```

However, parameters used inside RUQ and REQ must be typed by the user with a `dec` predicated inside the RQ:

```
dec(A,set(t)) & dec(F,rel(t,int)) &
foreach(X in A,[Y], Y > 0, applyTo(F,X,Y) & dec(Y,int)).
```

The typechecker doesn't support `forall` (Section 6.2) nor general existential quantifiers (Section 6.3).

12.4 Typing user-defined predicates

If you activate the typechecker and you want to consult a file containing a collection of $\{log\}$ clauses (i.e., a $\{log\}$ program), then you first need to type clauses of that file.

For instance, you may want to define a predicate adding a $(name,address)$ pair to the function holding the addresses of your acquaintances:

```
add_person(P,N,A,P_) :-
  pfun(P) & dom(P,D) & N nin D & P_ = {[N,A]/P}.
```

If you put this predicate in a file then you have to type the predicate, before loading the file in type-checking mode:

```
def_type(na,[name,address]).
dec_p_type(add_person(set(na),name,address,set(na))).
add_person(P,N,A,P_) :-
  dec(D,set(name)) &                                     [D is typed inside the clause]
  pfun(P) & dom(P,D) & N nin D & P_ = {[N,A]/P}.
```

The first line simply declares a name for the type `[name, address]`—this is optional. In the second line `dec_p_type/1` declares the type of `add_person` by giving the type of each and every argument. It can be read as “declare predicate type”. Then, for example, the first `set(na)` states that the first argument of `add_person` must be of that type; `name` states that the second argument of `add_person` must be of that type; and so on and so forth. Given that `D` is an internal variable we declare its type inside `add_person`.

A `dec_p_type` declaration must precede the definition of the corresponding predicate. If a predicate is defined in more than one clause, only one `dec_p_type` declaration must be in place. Directives and facts (i.e., unit clauses) are not typed.

Note that before re-consulting a file or consulting a new one, you have to reset all type declarations—see Section 12.10 to learn how to do this. The `abolish/0` command does not remove global information about types.

`dec_p_type/1` is a reserved word of the language when the typechecker is active. It cannot be used in other contexts.

12.5 Typing polymorphic operators

We have already shown that some operators are polymorphic. For example, we already know the type of these operators:

```
un(set(T), set(T), set(T))
comp(rel(T,U), rel(U,V), rel(T,V))
id(set(T), rel(T,T))
```

where `T`, `U` and `V` are *type variables*. That is, `T`, `U` and `V` are not types but they can be bound to types—recall that types and type constructors always begin with a lowercase letter.

You can define your own polymorphic operators and type them. For example, if you want to define the predicate `un3` which performs the union of three sets, you can write that definition in some file as follows:

```
dec_pp_type(un3(set(T), set(T), set(T), set(T))).
un3(A,B,C,D) :-
    dec(X, set(T)) &                                     [X typed with same type variable, T]
    un(A,B,X) & un(X,C,D).
```

`dec_pp_type/1` is the equivalent to `dec_p_type` for polymorphic predicates. It can be read as “declare polymorphic predicate type”. The difference between a `dec_pp_type` and a `dec_p_type` declaration is that the former accepts type variables, while the latter does not. `{log}` understands that predicate `p` is polymorphic if it is preceded by a `dec_pp_type(p(...))` declaration, where the arity of `p` must coincide with that of `p(...)` inside the `dec_pp_type` declaration.

Note that `X` in `un3` is typed with the same type variable, `T`, used in the `dec_pp_type` declaration; otherwise a type error will be informed. `dec` accepts type variables only when placed inside polymorphic predicates.

12.6 Running formulas in type-checking mode

If formulas are run when the typechecker is active, all variables must be declared to have exactly one type.

For example, if you want to call the `un3` predicate defined in the previous section you will have to give the type of each actual parameter:

```
{log}=> dec([W,X,Y,Z],set(t)) & un3(W,X,Y,Z).
```

Note that in the `dec` constraint we use a type, i.e. `t`, and not a type variable, e.g. `T`. Recall that elements of type `t` are of the form `t:elem` for any atom `elem`. So you can call `un3` as follows:

```
{log}=> dec([X,Y,Z],set(t)) & un3({t:a,t:aa},X,Y,Z).
```

Ordered pairs can also be used as expected. For example:

```
{log}=> dec([X,Y,Z],rel(t,u)) & dec(I,t) &
        un3({[I,u:abc]},X,Y,Z).
```

Similarly, the elements of `int` and `str` can be used in formulas:

```
{log}=> dec(Z,set(int)) & dec([I,J],int) &
        un3({1,2,3},{I,J},{},Z).
{log}=> dec(Z,set(str)) & dec([I,J],str) &
        un3({"Messi","Maradona","Di Stefano"},{I,J},{},Z).
```

12.7 `goalsol` when typechecking is active

`goalsol` can also be used in typechecking mode (see Section 3.2). Differently from the untyped case, in typechecking mode `goalsol` returns constants of the appropriate type for each variable. For example:

```
{log}=> dec(X,set([int,enum([a,b])])) & size(X,3).
```

```
X = {[0,b],[1,b],[2,b]}
```

```
{log}=> dec(X,set([t,str])) & size(X,3).
```

```
X = {[t:n0,n0],[t:n1,n1],[t:n2,n2]}
```

Observe the difference in the output when the same goals are run after turning off typechecking:

```
{log}=> notype_check.
```

```
{log}=> dec(X,set([int,enum([a,b])])) & size(X,3).
```

```
X = {n0,n1,n2}
```

```
{log}=> dec(X,set([t,str])) & size(X,3).
```

```
X = {n0,n1,n2}
```

Recall that type information is ignored when the typechecker isn't active. Then, `{log}` processes only `size(X,3)` in both goals. Since the elements of `X` have no type, `{log}` binds them to constants of the form `n⟨number⟩`, as explained at the end of Section 3.2.

On the contrary, when typechecking is active $\{log\}$ generates constants of the appropriate types. For instance, in the first goal the elements of X are ordered pairs whose first component is an integer number and the second is either a or b . In the second goal, the first components are of type t , whereas the seconds are of type str . Then, $t:n0$ is a first component because the elements of type t are of the form $t:\langle atom \rangle$, as explained in Section 12.1.3. In turn, the second components are of the form $n\langle number \rangle$ because they are strings.

In general, $\{log\}$ generates the following constants when `goalsol` is called in typechecking mode:

- $int \rightarrow 0, 1, -1, 2, -2, \dots$
- $str \rightarrow n0, n1, n2, \dots$
- basic type $t \rightarrow t:n0, t:n1, t:n2, \dots$
- sum types \rightarrow the nullary constructors are used as constants; if a non-nullary constructor x depends on type T then constants of the form $x(c)$, with c of type T , are generated.
- product type \rightarrow ordered pairs where the first components and the second components are constants of the corresponding types.
- set type \rightarrow the constants are singleton sets where the elements are of the corresponding type.

The combination between `goalsol` and type checking can't be used to solve user-defined predicates including existential variables.

12.8 Proving goals involving finite types

Clearly, the following goal is unsatisfiable:

$$\{log\} \Rightarrow dec(Z, enum([t, f])) \ \& \ Z \neq t \ \& \ Z \neq f.$$

because the only two values Z can take are exactly t and f . When working in typechecking mode, $\{log\}$ automatically transforms that goal into:

$$Z \text{ in } \{t, f\} \ \& \ Z \neq t \ \& \ Z \neq f.$$

thus answering no. However, if the typechecker isn't active, the same goal is found to be satisfiable because the `dec` predicate is ignored and Z can take any value beyond t and f .

As another example, consider the following goal:

$$\begin{aligned} & dec(F, rel(enum([t, f]), int)) \ \& \ pfun(F) \ \& \ F = \{X1, X2, X3\} \ \& \\ & dec([X1, X2, X3], [enum([t, f]), int]) \ \& \ X1 \neq X2 \ \& \ X1 \neq X3 \ \& \ X2 \neq X3. \end{aligned}$$

As F is a partial function and given the `neq` constraints, the first components of $X1$, $X2$ and $X3$ must be different from each other. At the same time, these first components have type `enum([t, f])`. So at least two of these first components must have the same value. Consequently the goal is unsatisfiable. As with the first goal, $\{log\}$ identifies this situation and automatically conjoin suitable membership constraints to make type information available to the constraint solver. Note that an alternative encoding of the above goal without types is:

```
foreach([X,Y] in F, X in {t,f} & integer(Y)) &
pfun(F) & F = {X1,X2,X3} &
X1 neq X2 & X1 neq X3 & X2 neq X3.
```

which is found to be unsatisfiable, as well. These situations arise when the formula involves finite types and entails, in a way or another, “too many” neq constraints involving variables whose type is finite. In this context T is a finite type if:

1. T is an enumerated type (i.e., a sum type with only nullary constructors).
2. T is the sum of finite types. This means that all the constructors of the sum type take values belonging to finite types.
3. T is the product of at least one finite type. One may be tempted to define this rule as: T is the product of finite types. However, the second example above shows that this alternative definition is wrong as `[enum([t,f]),int]` wouldn't be finite but that formula is unsatisfiable. Conversely, according to our definition, `[enum([t,f]),int]` is a finite type because `enum([t,f])` is a finite type.
4. T is the set type of a finite type.

12.9 Admissible terms in type-checking mode

In type-checking mode only terms that can be assigned a type are admissible. Then, for instance, `[a|[]]` is not an admissible term in type-checking mode:

```
{log}=> [a|[]] = 1.
type error: '[a]' doesn't fit in the sum type
```

Clearly, the admissible terms are correlated with the type system as follows:

- Variables – any type
- Integer numbers – type `int`
- Strings – type `str`
- Atoms – enumerated type
- Non-nullary terms – sum type
- Terms of the form `type:elem` where `type` and `elem` are atoms – type `type`
- Nested lists – product type
- `{}` – any set type
- Sets – set type
- Any syntactically correct term recursively constructed using the terms listed above.

All the other terms are not admitted. In particular, the type checker doesn't support general intensional set terms (Section 5.2).

12.10 User commands to work with types

The following user commands are available to deal with types when using `{log}` in interactive mode.

- `idef_type/2`. Besides being used for type declarations as described in Section 12.2, this command can be used to get the type expression associated to a type name by passing in a variable as a second argument.

For example, assuming that `t` is a type name for some type expression:

```
{log}=> idef_type(t,E).
E = set([obj,ac])
Another solution? (y/n)
no
```

- `reset_types/0` deletes all currently active type declarations. These include declarations made through the following predicates: `[i]def_type`, `dec_p_type` and `dec_pp_type`. This command should be used if a file is going to be re-consulted. Note that all the type declarations made in other loaded files or in interactive mode are also deleted.
- `type_of(pred)` where `pred` is an atom, prints the type of `pred` as given by either a `dec_p_type` or a `dec_pp_type` declaration for `pred`.

For example:

```
{log}=> type_of(dres).
dres(set(T),set([T,U]),set([T,U]))

yes
```

- `type_decs/1` where the parameter can be `td`, `pt` or `ppt`. It shows all the pairs (*type_name*, *type_expression*) (`td`); the type of all non-polymorphic predicates (`pt`); and the type of all polymorphic predicates (`ppt`); in all three cases, with respect to the currently active declarations.
- `expand_type(t,E)` where `t` is a type expression and `E` is a variable. If `t` is given in terms of type names, these are recursively replaced by the corresponding type expressions.

For example:

```
{log}=> idef_type(t,set(a)).
{log}=> idef_type(a,set(b)).
{log}=> expand_type(t,E).
E = set(set(b))
Another solution? (y/n)
no
{log}=> expand_type([t,a],E).
E = [set(set(b)),set(b)]
Another solution? (y/n)
no
```


13 Specifying and verifying state machines

The contents of this section and its implementation in `{log}` are still experimental

`{log}` can be used to specify state machines in a similar fashion as in set-based, state-based formal notations such as B [6] and Z [2]. Furthermore, `{log}` provides declarations that are used to automatically generate verification conditions on those state machines. Later, users can use `{log}` itself to automatically prove or disprove these verification conditions. We will show how to do that by encoding in `{log}` the classic birthday book problem used by Spivey to illustrate the Z formal notation.

The features described in this section can only be used if the file `setlog_vcg.pl` is present in the working directory.

13.1 The specification of the birthday book problem

In `{log}` a state machine is composed of:

1. Zero or more parameters
2. One or more state variables
3. Zero or more axioms
4. Zero or more state invariants
5. Possibly a predicate defining a set of initial states
6. One or more state operations (i.e., state transitions)
7. Zero or more theorems

Users must declare these elements in that order, except for theorems which can be declared anywhere in the specification after the first axiom.

We assume the birthday book specification is saved in a file named `bb.slog`.

Hence, we start by declaring the state variables of the birthday book. The birthday book is a system which records people's birthdays, and is able to issue a reminder when the day comes round. As Spivey, we will use two state variables: `Known`, holding the names of the people in our book; and `Birthday`, mapping names to birthdays. Then, we add the following fact at the beginning of file `bb.slog`:

```
variables([Known,Birthday]).
```

where `variables` is used to declare the state variables of a state machine. It receives as an argument a list of *distinct* variables—i.e., no constants or compound terms are allowed; the same variable cannot be more than once in the list. `variables` is a reserved word when it comes to the specification of state machines using `setlog_vcg.pl`. There can be only one `variables` declaration per state machine.

The intention is for `Known` to be the domain of `Birthday` and for the latter to be a partial function. As these properties are meant to be state invariants we introduce the following declarations and predicates:

```

invariant(birthdayBookInv).
birthdayBookInv(Known,Birthday) :- dom(Birthday,Known).

invariant(pfunInv).
pfunInv(Birthday) :- pfun(Birthday).

```

That is, before introducing the predicate stating an invariant we declare it to be an invariant by means of the `invariant` declaration—a reserved word. This declaration takes as its argument the head (without arguments) of the predicate stating the invariant.

There can be zero or more invariant declarations but any sensible state machine will have at least one of them. All the invariant declarations must appear right after the variables declaration and before other declarations we will shortly introduce. In turn, an invariant is a predicate that depends on at least one state variable. As can be seen, `birthdayBookInv` depends on the two state variables whereas `pfunInv` depends only on `Birthday`. Invariants may also depend on model parameters.

After introducing an invariant the user has to introduce its negation as well. So the above predicates are completed as follows.

```

invariant(birthdayBookInv).
birthdayBookInv(Known,Birthday) :- dom(Birthday,Known).
n_birthdayBookInv(Known,Birthday) :- neg(dom(Birthday,Known)).

invariant(pfunInv).
pfunInv(Birthday) :- pfun(Birthday).
n_pfunInv(Birthday) :- neg(pfun(Birthday)).

```

Recall Section 3.5 to know how to declare the negation of a user-defined predicate and the limitations of the `neg` connective. In particular, recall that `{log}` doesn't automatically compute the negation of these predicates.

Declaring that a predicate is an invariant *doesn't* mean that the state machine will indeed verify it. The invariant declaration is just a declaration of intent. However, `{log}` will use these declarations to automatically generate verification conditions that will make evident whether or not the state machine verifies these invariants—see Section 13.4.

We can combine the above declarations with type declarations as follows:

```

def_type(bb,rel(name,date)).
def_type(kn,set(name)).

invariant(birthdayBookInv).
dec_p_type(birthdayBookInv(kn,bb)).
birthdayBookInv(Known,Birthday) :- dom(Birthday,Known).
dec_p_type(n_birthdayBookInv(kn,bb)).
n_birthdayBookInv(Known,Birthday) :- neg(dom(Birthday,Known)).

invariant(pfunInv).
dec_p_type(pfunInv(bb)).

```

```

pfunInv(Birthday) :- pfun(Birthday).
dec_p_type(n_pfunInv(bb)).
n_pfunInv(Birthday) :- neg(pfun(Birthday)).

```

After introducing invariants we can introduce a predicate defining a set of initial states. In the case of the birthday book we have the following:

```

initial(birthdayBookInit).
dec_p_type(birthdayBookInit(kn,bb)).
birthdayBookInit(Known,Birthday) :-
    Known = {} &
    Birthday = {}.

```

As invariant, the `initial` declaration takes as argument the head of the predicate defining the initial state. `initial` is another reserved word.

There can be zero or one `initial` declaration in any given state machine but most of them will have one. The `initial` declaration must come after the last invariant (if any) and before the first operation. The predicate defining the initial states of the system must depend on at least one state variable, and may depend on model parameters.

The last component of a state machine is one or more state operations or state transitions. For example, in the birthday book we have an operation to remind the user of all the persons whose birthday is in a given date.

```

operation(remind).
dec_p_type(remind(kn,bb,date,kn,kn,bb)).
remind(Known,Birthday,Today,Cards,Known,Birthday) :-
    rres(Birthday,{Today},M) & dec(M,bb) &
    dom(M,Cards).

```

Again, the operation declaration takes as argument the head of the predicate defining the operation. It is a reserved word, too.

The above operation doesn't change the state of the system. We can tell that because there are no next-state variables in its head. A next-state variable is a state variable ending with the underscore character ('_'). For instance, `Known_` would be a next-state variable in the birthday book specification. In notations such as *Z*, `Known_` would have been written as *Known'*. The underscore character is a reserved symbol when it comes to the specification of state machines.

If an operation doesn't change the value of one of the state variables, then either:

- Include the variable *twice* in the operation's head (for example as in `remid` above). In this way, some users may see more clearly that the operation isn't changing that variable—for instance *Z* users because in *Z* one must explicitly indicate which variables are unchanged by an operation.
- Include the variable *once* in the operation's head. This may be closer to B specifications.
- Don't include the variable in the operation's head. If the variable isn't needed for that operation then just don't write it as an argument for that operation.

In any of these cases *{log}* will interpret that the operation doesn't change the value of that variable. Making explicit that an operation doesn't change a state variable allows *{log}* to infer some facts about the specification, as we will see in Section 13.4.

On the other hand, when an operation does change the value of a state variable we have to include the corresponding next-state variable in the head (and use it in the body). For example, the following operation adds a new birthday to the book:

```
operation(addBirthday).
addBirthday(Known,Birthday,Name,Date,Known_,Birthday_) :- ...
```

Then `Known_` and `Birthday_` are part of the operation's head.

The body of `addBirthday` is given as the disjunction between two predicates: the first, considers the case when the name whose birthday is going to be added is not in the book, and the second considers the opposite situation. The first case is covered by `addBirthdayOk`:

```
dec_p_type(addBirthdayOk(kn,bb,name,date,kn,bb)).
addBirthdayOk(Known,Birthday,Name,Date,Known_,Birthday_) :-
    Name nin Known &
    un(Known,{Name},Known_) &
    un(Birthday,{[Name,Date]},Birthday_).
```

The second case is covered by `nameAlreadyExists`:

```
dec_p_type(nameAlreadyExists(kn,name)).
nameAlreadyExists(Known,Name) :-
    Name in Known.
```

Note that we don't declare these predicates as operations. This is because we declare the predicate making the disjunction of them as the operation:

```
operation(addBirthday).
dec_p_type(addBirthday(kn,bb,name,date,kn,bb)).
addBirthday(Known,Birthday,Name,Date,Known_,Birthday_) :-
    addBirthdayOk(Known,Birthday,Name,Date,Known_,Birthday_)
    or
    nameAlreadyExists(Known,Name) & Known_ = Known & Birthday_ = Birthday.
```

It would be wrong to declare all three (and even two) of them as operations. Think of `addBirthdayOk` and `nameAlreadyExists` as auxiliary predicates used to define the operation. Auxiliary predicates shouldn't be declared as operations. Nonetheless, `{log}` won't be able to warn the user if this is happening. The problem with declaring auxiliary predicates as operations is that `{log}` will generate more verification conditions than necessary thus enlarging the verification process—see Section 13.4.

It is also not possible to first define `addBirthday` and then `addBirthdayOk` and `nameAlreadyExists` because when the typechecker finds `addBirthday` it cannot resolve the type of `addBirthdayOk` and `nameAlreadyExists` as it hasn't typechecked them already.

The birthday book offers an operation to find the birth date of a given person:

```
dec_p_type(findBirthdayOk(kn,bb,name,date)).
findBirthdayOk(Known,Birthday,Name,Date) :-
    Name in Known &
    applyTo(Birthday,Name,Date).
```

```

dec_p_type(notAFriend(kn,name)).
notAFriend(Known,Name) :-
    Name nin Known.

operation(findBirthday).
dec_p_type(findBirthday(kn,bb,name,date)).
findBirthday(Known,Birthday,Name,Date) :-
    findBirthdayOk(Known,Birthday,Name,Date)
or
    notAFriend(Known,Name).

```

As can be seen, this operation doesn't change the state of the system.

If V is a state variable and $V_$ is an argument of an operation then V must be another argument. Including $V_$ as an argument when V isn't a state variable is an error. Including $V_$ more than once is an error. If V is a state variable it can be included at most twice in the head of the operation.

13.2 Parameters, axioms and theorems

In this section we will explain how parameters, axioms and theorems can be used to specify state machines. If parameters are used they must be declared at the beginning of the specification, axioms must be included right after the declaration of state variables. Theorems can be declared anywhere after the first axiom.

Parameters play the role of machine parameters or constants in B specifications, and the role of variables declared in axiomatic definitions in Z. Axioms play the role of properties in B, and the role of predicates appearing in axiomatic definitions in Z. That is, parameters serve to declare the existence of some (global) values accessible to invariants and operations, but they cannot be changed by operations. Axioms, in turn, can be used to state properties of parameters. In fact, an axiom can only depend on parameters—i.e., axioms *can't* depend on state variables or any other kind of variables.

As an example, consider a specification dealing with users and their passwords. We are interested in stating that passwords are stored in an encrypted form but we don't want to specify a particular encryption algorithm or cryptographic hash function. In this case we can work as follows:

```

parameters([Password,CryptoHash,Hash]).

axiom(axm1).
axm1(CryptoHash) :- pfun(CryptoHash).

axiom(axm2).
axm2(Password,CryptoHash) :- dom(CryptoHash,Password).

axiom(axm3).
axm3(CryptoHash,Hash) :- foreach([X,Y] in CryptoHash, Y in Hash).

```

From now on, we can use Password, CryptoHash and Hash as arguments in invariants, operations and theorems. However, including CryptoHash_ (i.e., an after state variable) as an argument in an operation will make $\{log\}$ to issue an error.

Theorems are used to state properties that can be deduced from axioms, invariants, operations or theorems that have already been declared. For this reason, theorems can only be declared after the first axiom.

For example, if we have:

```
variables([X,Y,Z]).
```

```
invariant(inv1).
inv1(X) :- 0 <= X.
```

```
invariant(inv2).
inv2(Y) :- 0 <= Y.
```

then we can declare the following theorem statement:

```
theorem(thrm1).
thrm1(X,Y) :- 0 <= X + Y.
```

for which we provide a proof:

```
proof_thrm1(X,Y) :- neg(inv1(X) & inv2(Y) implies thrm1(X,Y)).
```

and the negation of thrm1 (as we do with invariants):

```
n_thrm1(X,Y) :- neg(0 <= X + Y).
```

The proof of a theorem statement named $th(x_1, \dots, x_m)$ must be a clause named `proof_th` located right after th and whose body must be of the form:

```
neg(h1 & h2 & ... & hn implies th(x1, ..., xm))
```

where each h_i must be an axiom, invariant, operation or theorem already declared. Note that the proof of a theorem is stated as an unsatisfiability condition.

In this way, $\{log\}$ will include verification conditions ensuring that the proofs of theorems are correct so users can use the theorem statements as hypotheses for other verification conditions.

13.3 Execution of state machines

Any predicate defined in the $\{log\}$ specification of a state machine can be called as any $\{log\}$ predicate. Therefore, the specification can be seen as an executable prototype where operations implement the prototype's functionality. Executions of the specification's operations can be performed to spot errors early on, analyze complex scenarios, analyze interactions among the operations, etc. Later, properties such as invariant preservation can be proved (Sect. 13.4).

Let's see an example of an execution assuming the specification of the birthday book has been saved in a file called `bb.slog`.

```
{log}=> consult('bb.slog').
```

```
{log}=> birthdayBookInit(K,B) & addBirthday(K,B,messi,240687,K_,B_).
```

```
K = {},
```

```
B = {},
```

```
K_ = {messi},
```

```
B_ = {[messi,240687]}
```

Another solution? (y/n) y

no

In this execution, the predicate setting the initial state (`birthdayBookInit`) is called followed by a call to one of the operations (`addBirthday`). Note how state variables are chained between predicates: `K` and `B` are passed in to `birthdayBookInit` and then passed in as the initial state to `addBirthday`. Actually, we can call more than one operation in the same execution:

```
{log}=> birthdayBookInit(K,B) &
        addBirthday(K,B,messi,240687,K1,B1) &
        addBirthday(K1,B1,'Pele',231040,K_,B_).
```

```
K = {},
```

```
B = {},
```

```
K1 = {messi},
```

```
B1 = {[messi,240687]},
```

```
K_ = {messi,Pele},
```

```
B_ = {[messi,240687],[Pele,231040]}
```

If we don't need the complete execution trace of a simulation but only its final state and outputs, then we can define a clause for the simulation whose arguments are the variables we are interested in:

```
sim(K_,B_) :-
    birthdayBookInit(K,B) &
    addBirthday(K,B,messi,240687,K1,B1) &
    addBirthday(K1,B1,'Pele',231040,K_,B_).
```

```
{log}=> sim(K,B).
```

```
K = {messi,Pele},
```

```
B = {[messi,240687],[Pele,231040]}
```

We can use variables instead of constants for input parameters but in that case we might get a list of constraints (not only equalities) and many variables, but at the same time we'll be able to conclude more general properties about the specification.

```
{log}=> birthdayBookInit(K,B) &
        addBirthday(K,B,N1,D1,K1,B1) &
        addBirthday(K1,B1,N2,D2,K_,B_).
```

```

K = {},
B = {},
K1 = {N1},
B1 = {[N1,D1]},
K_ = {N1,N2},
B_ = {[N1,D1],[N2,D2]}
Constraint: N1 neq N2

```

Constraints and variables can be avoided in the computed answer if executions are run in `goalsol` mode (Sect. 3.2), but in this case the results are less general.

```

{log}=> goalsol.
{log}=> birthdayBookInit(K,B) &
        addBirthday(K,B,N1,D1,K1,B1) &
        addBirthday(K1,B1,N2,D2,K_,B_).

```

```

K = {},
B = {},
N1 = n0,
D1 = n3,
K1 = {n0},
B1 = {[n0,n3]},
N2 = n1,
D2 = n2,
K_ = {n0,n1},
B_ = {[n0,n3],[n1,n2]}

```

13.4 Automatic generation of verification conditions

Once we have defined a state machine as described above, we can use the Verification Condition Generator (VCG) to help in its verification. The VCG generates some verification conditions that, when successfully discharged, will give some confidence on the correctness of the specification. `{log}` itself can be used to automatically prove or disprove these verification conditions.

Assuming the birthday book specification is saved in file `bb.slog`, the user can issue the following commands to generate the verification conditions associated to this specification:

```

{log}=> consult('bb.slog').
{log}=> vcg('bb.slog').

```

In this way, `{log}` generates a file named `bb-vc.slog` containing the verification conditions. The file is consulted as usual:

```

{log}=> consult('bb-vc.slog').

```

If `vcg` is called more than once on the same file, the corresponding `-vc` file will be overwritten, thus loosing any changes introduced by the user.

The main predicate in that file is named `check_vcs_bb`. When this command is run, `{log}` attempts to discharge all the verification conditions:

```
{log}=> check_vcs_bb.

Checking birthdayBookInit_sat_birthdayBookInv ... OK
Checking birthdayBookInit_sat_pfunInv ... OK
Checking addBirthday_is_sat ... OK
Checking findBirthday_is_sat ... OK
Checking remind_is_sat ... OK
Checking addBirthday_pi_birthdayBookInv ... OK
Checking addBirthday_pi_pfunInv ... ERROR
Checking findBirthday_pi_birthdayBookInv ... OK
Checking findBirthday_pi_pfunInv ... OK
Checking remind_pi_birthdayBookInv ... OK
Checking remind_pi_pfunInv ... OK
```

Note that `{log}` is able to discharge all but one of the verification conditions (`addBirthday_pi_pfunInv`).

In general, the command used to discharge proof obligations is named `check_vcs_⟨fileName⟩`, where `fileName` is the name of the file containing the specification of the state machine. This command expects no arguments. There are two more commands with the same name but different arities:

- `check_vcs_⟨fileName⟩(+Timeout,+OptList)` where `Timeout` must be a positive number indicating a timeout measured in milliseconds and `OptList` is any term accepted by `setlog/5` in its fifth argument as documented in Sect. 15.1. The timeout is used for *each* proof obligation—for example, in the birthday book the maximum time this command can take is `11*Timeout` milliseconds because there are 11 verification conditions. Some examples of this command are the following:

```
{log}=> check_vcs_bb(1000,[subset_unify,comp_fe]).
```

```
{log}=> check_vcs_bb(2000,try(prover_all)).
```

- `check_vcs_⟨fileName⟩(+OptList)` is implemented as:

```
check_vcs_⟨fileName⟩(60000,OptList).
```

- `check_vcs_⟨fileName⟩` is implemented as:

```
check_vcs_⟨fileName⟩(60000,[]).
```

13.5 Analyzing undischarged verification conditions

`{log}` may not be able to discharge a verification condition for many reasons. If a verification condition falls outside the decision procedures implemented in `{log}`, then the tool will be unable to discharge it. There's nothing to do in these cases. If the specification is wrong (e.g., a precondition is missing, an invariant is too strong, etc.) then it may be impossible to prove

some verification condition. In these cases the counterexamples returned by `{log}` can be of much help (Section 13.5.1). Finally, a verification condition may require more hypotheses, as explained in Section 13.5.2.

13.5.1 Counterexamples of undischarged verification conditions

When a verification condition such as `addBirthday_pi_pfunInv` remains undischarged, `{log}` saves a counterexample. These counterexamples can be very helpful in finding out why the proof failed. There are two kinds of counterexamples: abstract and ground. Abstract counterexamples may include many variables; ground counterexamples bind a ground term to every variable (recall Section 3.2).

Let's see the abstract counterexample of `addBirthday_pi_pfunInv`:

```
{log}=> vcace(addBirthday_pi_pfunInv).

Birthday = {[Name,_25302]/_25228}
Known_ = {Name/Known}
Birthday_ = {[Name,Date],[Name,_25302]/_25228}

Constraints: pfun(_25228) & compPf([Name,Name],_25228,{}) &
           Name nin Known & Date neq _25302
```

As can be seen, `vcace`²⁰ receives the name of a verification condition as its sole argument and prints a counterexample containing many variables (e.g. `_25302`) besides those used in the specification.

This counterexample helps to understand why `addBirthday_pi_pfunInv` failed. In effect, notice that `Name` is in the domain of `Birthday` but it doesn't belong to `Known` (see the constraint `Name nin Known`). This is in contradiction with invariant `birthdayBookInv` which states that `Known` must be the domain of `Birthday`. Given that we have proved that `birthdayBookInv` is indeed an invariant we can include it as an hypothesis to prove `addBirthday_pi_pfunInv`—see how to do that in Section 13.5.2.

The ground counterexample can be seen with command `vcgce` (g for ground):

```
{log}=> vcgce(addBirthday_pi_pfunInv).

Birthday = {[n2,n1]}
Known = {}
Name = n2
Date = n0
Known_ = {n2}
Birthday_ = {[n2,n0],[n2,n1]}
```

We can see again that `Known` is empty while `Birthday` is not thus contradicting `birthdayBookInv`.

²⁰`vcace` stands for *verification condition abstract counterexample*.

13.5.2 The `findh` command family

`{log}` was unable to discharge `addBirthday_pi_pfunInv` because of the way it generates verification conditions. This point is treated more deeply in Section 13.6. For the moment, it suffice to say that `{log}` generates each verification condition with the minimum number of hypotheses. In consequence, `{log}` is sometimes unable to discharge a verification condition because there are some missing hypotheses. Missing hypotheses can only be found among the axioms and invariants declared in the specification.

The `findh` family of commands helps users to find missing hypotheses in verification conditions whose proofs failed (as with `addBirthday_pi_pfunInv`). However, before calling these commands take a look at the counterexamples returned by `{log}` because in many cases they provide enough information to solve the problem. The simplest way of finding missing hypotheses (although in some cases it will take a long time), is by running the `findh` command:

```
{log}=> findh.
Missing hypotheses for addBirthday_pi_pfunInv: [[birthdayBookInv]]
```

Now we can add `birthdayBookInv` as an hypothesis of `addBirthday_pi_pfunInv`. In order to do that, we edit `bb-vc.slog`, look up `addBirthday_pi_pfunInv` and modify it as follows (as the comment suggests):

```
addBirthday_pi_pfunInv :-
  birthdayBookInv(Known,Birthday) &                %% NEW HYPOTHESIS
  neg(
    pfunInv(Birthday) &
    addBirthday(Known,Birthday,Name,Date,Known_,Birthday_) implies
    pfunInv(Birthday_)
  ).
```

Later, the user should consult `bb-vc.slog` again and run `check_vcs_bb`. If the proof fails, `findh` can be called again in which case it will probably find other hypotheses.

If `vcg` is called more than once on the same file, the corresponding `-vc` file will be overwritten, thus loosing all hypothesis added by the user.

`findh` goes through all the failed proofs searching for missing hypotheses for each of them. It first tries with each axiom and invariant as a possible hypothesis. In some cases, the conjunction of two or more axioms or invariants are necessary to prove a given verification condition. For this reason, if `findh` couldn't find a single axiom or invariant, it tries by conjoining two of them; if this isn't enough, `findh` will try with conjunctions of three axioms and invariants. This process continues until the conjunction of all axioms and invariants is tried out. In specifications with more than 10 to 15 axioms and invariants the number of conjunctions of 2, 3 or more elements will be computationally prohibitively.

As a consequence, `{log}` provides also the following `findh` and `findhn` commands based on the same idea:

- `findh(vc)` where `vc` is the identifier of a verification condition (e.g. `addBirthday_pi_pfunInv`). Works as `findh` but only for `vc`.

- `findh(vc,n,o|e,axinvs)` where `vc` is the identifier of a verification condition (e.g. `add-Birthday_pi_pfunInv`), `n` is a positive natural number, `o|e` is either the atom `o` or `e`, and `axinvs` is a list of axiom or invariants identifiers. This command works as `findh` but only for `vc` and by applying the following restrictions.
 - It will attempt with conjunctions of exactly `n` axioms or invariants.
 - If the third argument is `o` it will use *only* the axioms and invariants passed in `axinvs`.
 - If the third argument is `e` it will *exclude* the axioms and invariants passed in `axinvs`.
- `findhn(n)` where `n` is a positive natural number. Works as `findh` but only with conjunctions of exactly `n` axioms or invariants.
- `findhn(vc,n)` where `vc` is the identifier of a verification condition (e.g. `add-Birthday_pi_pfunInv`), and `n` is a positive natural number. Works as `findh` but only for `vc` and only with conjunctions of exactly `n` axioms or invariants.

Observe that, in general, more than one conjunction of axioms or invariants can be a missing hypothesis. When this is the case, the `findh` commands will print a list with all of them. So, for example:

```
{log}>= findh.
Missing hypotheses for xxx_pi_yyy: [[ax1,inv3],[inv2,inv4]]
Missing hypotheses for vvv_pi_www: [[ax3],[inv3],[inv4]]
```

means that the conjunction of `ax1` and `inv3` and the conjunction between `inv2` and `inv4` are missing hypothesis for the verification condition named `xxx_pi_yyy`; and that `ax3`, `inv3` and `inv4` are missing hypothesis for `vvv_pi_www`. In these cases, the user should evaluate which of the missing hypothesis is the most promising to conclude the proof of the corresponding verification condition.

13.6 Verification conditions generated by the VCG

The VCG generates the following verification conditions. The examples given below correspond to the birthday book specification (when possible).

1. The conjunction of all axioms is satisfiable (`axioms_sat`).
2. The initial state satisfies each and every invariant (`_sat_`). As an example we have:

```
birthdayBookInit_sat_birthdayBookInv :-
  birthdayBookInit(Known,Birthday) &
  birthdayBookInv(Known,Birthday).
```

If there's no initial state, then the proof obligation checks that each invariant is satisfiable.

3. Each operation is satisfiable and can change the state (`_is_sat`). For example:

```
addBirthday_is_sat :-
  addBirthday(Known,Birthday,Name_i,Date_i,Known_,Birthday_) &
  [Known,Birthday] neq [Known_,Birthday_].
```

If the operation doesn't change state variables, then the proof obligation checks satisfiability of the operation. For example:

```

findBirthday_is_sat :-
    findBirthday(Known,Birthday,Name,Date).

```

4. All `applyTo` predicates appearing as a functional predicate in a `foreach` constraint are well-defined (`_is_wd_`). More precisely, if `applyTo(F,X,Y)` appears in a `foreach` constraint whose quantification variable is `X`, then the verification condition ensures that `X` belongs to the domain of `F`.
5. *Invariance lemmas*: each operation preserves each and every invariant (`_pi_`). For example:

```

addBirthday_pi_birthdayBookInv :-
    % here conjoin other ax/inv as hypothesis if necessary
    neg(
        birthdayBookInv(Known,Birthday) &
        addBirthday(Known,Birthday,Name,Date,Known_,Birthday_) implies
        birthdayBookInv(Known_,Birthday_)
    ).

```

6. *Theorems*: the proofs of user-defined theorems are included as verification conditions. Since `{log}` will try to prove their unsatisfiability, proofs must encode unsatisfiable formulas.

The most important verification conditions are the invariance lemmas. However, if the operation or the invariant are unsatisfiable the invariance lemma will trivially hold. Hence, the VCG also generates the first two satisfiability verification conditions.

14 Control predicates

`{log}` provides a number of built-in predicates that can be used by the user to interact with the control mechanisms of the interpreter. We will distinguish these predicates into three categories: general predicates, predicates for controlling constraint solving, predicates for execution monitoring.

14.1 General

- `call(G)`, `call(G,C)`: to execute goal `G`, possibly getting constraint `C`.
- `solve(G)`: same as `call(G)` but all constraints possibly generated by `G` are immediately solved; moreover, `G` is always executed in solver mode (cf. Section 3.7). For example:

```
{log}=> diff({1,2,3},{2},S).
```

makes `{log}` to answer

```
S = {1,3/_N1} Constraint: subset(_N1,{1,2,3}), set(_N1), 2 nin _N1
```

while by issuing

```
{log}=> solve(diff({1,2,3},{2},S)).
```

you get the answer

```
S = {1,3}
```

As another example (comparing `call` and `solve`):

```
{log}=> mode(solver).
{log}=> call(inters(X,{a,b},Z))& write(Z).
{log}=> solve(inters(X,{a,b},Z))& write(Z).
```

generate the same answers, but the call to `write(Z)` in the second goal prints the internal representation of an uninitialized variable (e.g., `_45554`) since the constraint `inters` is automatically delayed if the third argument and one of the first two are uninitialized variables, while `write(Z)` in the third goal prints `{a,b}`, i.e., the first solution for `Z`.

- `G!`: to make execution of goal `G` deterministic.

Comments about `G!`. `{log}` does not provide the general ‘cut’ facility of Prolog. In `{log}`, however, it is possible to make the execution of a goal `G` *determinate* by putting the `cut` symbol just after the goal `G`. `G!`, where `G` is any `{log}` goal, is executed exactly as `G` except that when `G` succeeds all (possibly none) alternative solutions for `G` are discarded. Thus, only the first solution for `G` is computed: if backtracking should later return to this goal, no further solutions will be found.

As an example:

```
{log}=> X in {a,b}!.
X = a
Another solution? (y/n)y
no
```

whereas the same goal without ‘cut’ would return the two distinct solutions `X = a` and `X = b`.

Note that the ‘cut’ operator applies to any `{log}` goal, including disjunctions, conjunctions (e.g., `(X in {a,b} & Y in {c,d})!`), RUQs, user and system defined predicates.

14.2 Constraint solving

- `delay(G,C)`, where `G` and `C` are `{log}` formulas: to delay execution of `G` until either `C` becomes true or the computation ends
- `strategy(S)`: to change goal predicate selection strategy:
 - `S = cfirst`: select constraints first
 - `S = ordered`: select all predicates in the order they occur
 - `S = cfirst(list_of_preds)`: select predicates in `list_of_preds` just after constraints.

Default selection strategy: `cfirst`.

- `noirules/0`, `irules/0`: to deactivate/activate inference rules (default: `irules`)
- `noneq_elim/0`, `neq_elim/0`: to deactivate/activate elimination of *neq*-constraints (default: `neq_elim`).

Comments about `strategy(S)`. Predicates in a goal are executed left-to-right in the order they appear in the goal, except that atomic constraints are executed before any other non-constraint atoms occurring in the goal. This default strategy can be changed by using the built-in predicate `strategy` as shown in the following examples.

Given the goal:

```
{log}=> write(b) & write(X) & X in {a}.
```

we get as answer (using the default strategy `cfirst`):

```
ba
X = a
```

that is, the constraint `X in {a}` is executed first (thus binding `X` to `a`), then the other predicates, `write(b)` and `write(X)`, are taken into account. Conversely, if we give first the goal `strategy(ordered)`, then the same goal as above will produce the answer (`_5044` is the system generated name of the uninitialized variable `X`):

```
b_5044
X = a
```

since predicates are executed in the exact order they occur in the goal²¹. Finally, if we give first the goal `strategy(cfirst([nl]))` then any predicate `nl` ("new line") possibly occurring in the next goals will be executed just before any other non-constraint predicates. For example:

```
{log}=> write(b) & write(X) & nl & X in {a}.
```

we get as answer

```
ba
X = a
```

where the blank line before `ba` is caused by the execution of `nl` before that of the built-in predicates `write`.

Note that `call(G)` and `solve(G)` are dealt with as non-constraint predicates, even when `G` is a constraint. Then `call` and `solve` can be used to influence the execution order of predicates in the formula. For example in:

```
solve(G1) & solve(G2)
```

`G1` is definitely executed *before* `G2`.

14.3 Execution monitoring

- `trace(Mode)`: to activate constraint solving tracing:
 - `Mode = sat`: general tracing
 - `Mode = irules`: inference rules tracing
- `notrace/0`: to deactivate constraint solving tracing (default)
- `time(G,T)`: to get the CPU time `T` (in milliseconds) required to solve the `{log}` goal `G` (using .

²¹With the exception of equalities which are in any case considered before any other non-constraint predicate.

15 Prolog- $\{log\}$ communication

15.1 From Prolog to $\{log\}$

Main predicates

- `setlog(+Goal,+Timeout,-OutConstrList,-Res,+OptList)`: to execute a $\{log\}$ goal `Goal` with an output constraint list `OutConstrList` and a timeout `Timeout` (an integer constant specifying an amount of time in milliseconds), with a (possibly empty) list `OptList` of execution options. The `Res` argument is used to specify how execution of `Goal` terminates: `success`, if `Goal` terminates successfully within the time `Timeout`; `time_out`, if `Goal` does not terminate within the time `Timeout`; `maybe`, if `Goal` terminates successfully within the time `Timeout` but the computed result is not guaranteed to be reliable.

The possible execution options are those specified by the built-in control predicates mentioned in the previous sections (in particular in sections 11 and 14). A complete list of the available execution options can be found in Appendix A. As an example, the following goal:

```
?- setlog(X in int(1,5),1000,C,R,
        [int_solver(clpfd),nolabel]).
```

requires the goal `X in int(1,5)` to be executed, with a 1000 millisecond timeout, using CLP(FD) as the integer solver but disabling the final automatic labeling step (see Sect. 7.1.1).

Options `type_check` and `groundsol` have no effect with `setlog/5`. If they are needed, then use predicates `setlog_str` or `setlog_tc`, as described below.

- `setlog(+Goal,+Timeout,-OutConstrList,-Res,+try([OptList1,...,OptListn]))`: as `setlog/5` in the previous item, but possibly attempting goal `Goal` as many times as the number of `OptListi` occurring in the argument of term `try`. Precisely, for each $i \in 1..n-1$, if the call:

```
setlog(Goal,Timeout,OutConstrList,OptsLsti)
```

terminates with a timeout, then the call:

```
setlog(Goal,Timeout,OutConstrList,Res,OptsLsti+1)
```

is attempted next; otherwise, the initial call terminates. As an example, the following goal:

```
?- setlog(dom(R,S) & ran(R,{1/S}),2000,C,Res,
        try([],[noran_elim])).
```

requires the goal `dom(R,S) & ran(R,{1/S})` to be executed, the first time, with a 2000 millisecond timeout and no execution options enforced; since this call terminates with a timeout, then the goal `dom(R,S) & ran(R,{1/S})` is executed again, with a 2000 millisecond timeout but activating the `noran_elim` option.

Note that, when `setlog/5` is called with the `try` option, the total execution time might be as large as $T * n$, where n is the number of `OptList` occurring in the `try` list.

Also, note that when using any of the execution options `noran_elim`, `nocomp_elim`, `noneq_elim`, the solver is no longer guaranteed to be complete; that is, given a goal G , if the answer is no, then G is surely unsatisfiable; otherwise, it is not guaranteed, in general, that G is satisfiable and the answer we get may be unreliable. In the latter case, the `Res` argument of the `setlog/5` predicate will be bound to the constant `maybe`.

- `setlog(+Goal,+Timeout,-OutConstrList,-Res,try(prover_all))`: is implemented as the following call to the `setlog/5` predicate.

`setlog(+Goal,+Timeout,-OutConstrList,-Res,try([s1,...,sn]))`

where $\{s_1, \dots, s_n\} = \mathbb{P}(\text{prover_all_strategies})$. That is, all the possible combinations of the current value of `prover_all_strategies` are attempted, including passing in no options (see also Sect. 11.3).

- `setlog(+Goal,+Timeout,-OutConstrList,-Res,try(prover_all_single))`: is implemented as the following call to the `setlog/5` predicate.

`setlog(+Goal,+Timeout,-OutConstrList,-Res,try([[s1],..., [sn]]))`

where $[s_1, \dots, s_n]$ is the current list of options returned by `prover_all_strategies`.

- `setlog(+Goal,+Timeout,-OutConstrList,-Res,+tryp([OptLst1,...,OptLstn]))`: the first four arguments work as in `setlog/5`; each `OptLsti` is as above. In this case `{log}` creates n (operating system) threads each of which executes `Goal` with one of `OptLsti` as the active execution options. The execution of the command terminates as soon as one thread terminates. This command is incompatible with non-determinism. Then, if the goal is satisfiable only the first solution is returned.
- `setlog(+Goal,+Timeout,-OutConstrList,-Res,try(prover_all))`: is implemented as `setlog/5` with option `try(prover_all)` (see above) but execution is parallelized as in the previous case.
- `setlog(+Goal,+Timeout,-OutConstrList,-Res,try(prover_all_single))`: is implemented as `setlog/5` with option `try(prover_all_single)` (see above) but execution is parallelized as in the previous case.
- `setlog(+Goal,+Timeout,-OutConstrList,-Res)`: is exactly as `setlog/5` but using a default value for the fifth argument, namely:

`try([[int_solver(clpfd)], [int_solver(clpq), final],
[noirules], [noneq_elim], [noran_elim]]).`

- `setlog(+Goal,-OutConstrList,-Res)`: is implemented as the following call to the `setlog/5` predicate.

`setlog(Goal,∞,OutConstrList,Res,[])`

That is, `setlog/3` is equivalent to a call to `setlog/5` with an infinite timeout and an empty list of execution options.

- `setlog(G,OutCLst)`: is implemented as the following call to the `setlog/3` predicate.

`setlog(Goal,OutConstrList,_)`

- `setlog(G)`: is implemented as the following call to the `setlog/2` predicate.

```
setlog(Goal,_)
```

- `rsetlog(+Goal,+Timeout,-OutConstrList,-Res,+OptList)`: same as `setlog/5`, but with “reification” on `Res`; specifically, if the execution of goal `G` terminates with failure, then `Res` is unified with `failure`; otherwise, `Res` is unified with either `success`, `time_out` or maybe as with `setlog/5`.
- `setlog`: to enter/re-enter the `{log}` interactive environment.
- `setlog_str(+GoalString,+PrologVars,+TimeOut,-OutConstrList,-Res,+OptList)`: `GoalString` is a `{log}` goal encoded as a string; `PrologVars` is a list of terms of the form `Name = Var`, where `Name` is an atom describing a variable name in `GoalString` and `Var` is a variable; and `OutConstraintList`, `Res` and `OptList` are as in `setlog/5`. `GoalString` is turned into a term but, in some way, if `X` is a variable in `GoalString` and there’s an equality `'X' = A` in `PrologVars` then `X` is substituted by `A` in `GoalString` before the execution of the goal is started. After this, the goal is executed as in `setlog/5`.

For example:

```
?- setlog_str(
    "X = 1 & un({1},{2},V) & un(V,Q,E)",
    ['X' = A, 'V' = V, 'Q' = X, 'E' = E],
    10000,C,R,[groundsol]).
```

produces as a result:

```
A = 1, V = E, E = {1, 2}, X = {},
C = [], R = success.
```

The example is clear on the effect of the `PrologVars` parameter. Besides, as can be seen, `setlog_str/6` is able to correctly execute when `groundsol` (and `type_check`, although not shown) is passed as an option.

If the user doesn’t want to write down the list for `PrologVars`, (s)he can use Prolog’s `term_string/3`:

```
?- G = "X = 1 & un({1},{2},V) & un(V,Q,E)",
    term_string(_,G,[variable_names(VN)]),
    setlog_str(G,VN,10000,C,R,[groundsol]).
```

In this case, if the user needs to reuse some variable in `GoalString`, then (s)he can use some member predicate as follows:

```
?- G = "X = 1 & un({1},{2},V) & un(V,Q,E)",
    term_string(_,G,[variable_names(VN)]),
    setlog_str(G,VN,10000,C,R,[groundsol]),
    member('V' = V,VN),
    write('\n\nThe result of the first union is: '), write(V), nl.
```

- `setlog_str(+GoalString,-EqsString,+TimeOut,-ConstrString,-Res,+OptList)`: same as `setlog_str/6` above but in this case the predicate doesn’t receive `PrologVars` but

instead it will return in `EqsString` a (possibly empty) list of strings each of which is of the form `Var=term` where `Var` is one of the free variables of `GoalString`. These equalities are the equalities that Prolog would normally output as part of any predicate answer. This means that no binding of terms to variables will be returned except for those in `EqsString`. In the same sense, `ConstrString` is a list of strings each of which is one of the constraints that `{log}` would normally return as part of its answer.

For example:

```
?- setlog_str(
    "X = 1 & un({1},{2},V) & un(V,Q,E)",
    Eqs,10000,C,R,[groundsol]).
```

produces as a result:

```
Eqs = ["'X'=1", "'V'={1,2}", "'Q'={}", "'E'={1,2}"],
C = [], R = success.
```

- `setlog_str(+GoalString,+PrologVars,-OutConstrList,-Res)`
`setlog_str(+GoalString,-EqsString,-ConstrString,-Res)`: are implemented as the following call to the `setlog_str/6` predicate.

```
setlog_str(GoalString,Vars_or_Eqs,∞,Constr,Res,[])
```

- `setlog_str(+GoalString,+PrologVars,-OutConstrList)`
`setlog_str(+GoalString,-EqsString,-ConstrString)`: are implemented as the following call to the `setlog_str/4` predicate.

```
setlog_str(GoalString,Vars_or_Eqs,Constr,_)
```

- `setlog_str(+GoalString,+PrologVars)`
`setlog_str(+GoalString,-EqsString)`: are implemented as the following call to the `setlog_str/4` predicate.

```
setlog_str(GoalString,Vars_or_Eqs,_,_)
```

- `rsetlog_str(+GoalString,+PrologVars,+Timeout,-OutConstrList,-Res,+OptList)`
`rsetlog_str(+GoalString,-EqsString,+Timeout,-ConstrString,-Res,+OptList)`: same as `setlog_str/6` but with “reification” on `Res`; see `rsetlog/5` for more details.

- `setlog_tc(+GoalString,+PrologVars,-OutConstrList)`
`setlog_tc(+GoalString,-EqsString,-ConstrString)`: are implemented as the following call to the `setlog_str/6` predicate.

```
setlog_str(GoalString,Vars_or_Eqs,∞,Constr,_,[type_check])
```

Other predicates. Besides the already mentioned predicates `setlog_consult/1` and `consult_lib/0` (see Sect. 2), `{log}` provides a few other built-in predicates that can be called directly from the Prolog environment:

- `setlog_clause(C1)`: to dynamically add a `{log}` clause `C1` to the current `{log}` program

- `setlog_config(list_of_params)`: to modify some `{log}` configuration parameters directly from the Prolog environment. Each parameter in `list_of_params` can be:
 - `path(Path)`: `Path` is the pathname of the directory to be used to prefix the name of any file which is loaded in `{log}` through the `consult` predicates (default: `'.'`)
 - `rw_rules(File)`: `File` is the name of the file containing the “filtering rules” (default: `'setlog_rules.pl'`);
 - `strategy(S)`: see the control predicate strategy in Sect. 14.

15.2 From `{log}` to Prolog

General

- `prolog_call(G)`: to execute any Prolog goal `G` from `{log}`.

Specific Prolog built-in predicates The following Prolog built-in predicates are directly available in `{log}` for user convenience:

- `nl/0`
- `ground/1`
- `var/1`
- `nonvar/1`
- `name/2`
- `functor/3`
- `arg/3`
- `=../2`
- `==/2`
- `\==/2`
- `@</2`
- `@>/2`
- `@=</2`
- `@>=/2`

16 The `{log}` library

A number of common predicates, dealing with sets and lists, which are not implemented as built-in predicates by the interpreter, are provided as user defined predicates by the standard `{log}` library `setloglib.slog`. The file `setloglib.slog` can be loaded as part of any `{log}` program using the built-in predicate `consult_lib/0`.

Below we list most of the predicates currently contained in `setloglib.slog`.

Dealing with sets

- `binters(S,R)`: generalized intersection: `R` is the intersection of all elements of the set of sets `S`
- `bun(S,R)`: generalized union: `R` is the union of all elements of the set of sets `S`

- `dint_to_set(A,B,S)`: same as `int_to_set/2` but delayed if interval limits are unknown
- `eq(T1,T2)`: syntactic unification between terms T1 and T2
- `int_to_set(I,S)`: S is the set of all elements of the interval I
- `list_to_set(L,S)`: S is the set of all elements of the list L
- `powerset(S,PS)`: powerset ($PS = 2^S$)
- `set_to_list(S,L)`: S is a set and L is a list containing all and only the elements of S, without repetitions (all possible permutations of L).

Dealing with lists

- `extract(S,L,NewL)`: S is a set of integer numbers, L is a list of elements of any type, and NewL is a list containing the *i*-th element of L, for all *i* in S (e.g., `extract({4,2},[a,h,g,m,t,r],L)` returns `L = [h,m]`)
- `drop(N,L,NewL)`: NewL is L with its first N elements removed
- `filter(L,S,NewL)`: L is a list, S is a set, and NewL is a list containing the elements of L that are also elements of S (e.g., `filter([a,h,g,m,t,r],{m,h,s},L)` returns `L = [h,m]`)
- `prefix(P,L)`: list P is a prefix of list L
- `sublist(Sb,L)`: list Sb is a sublist of list L
- `take(N,L,NewL)`: list NewL consists of the first N elements of list L.

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A $\{log\}$ commands and execution options

The following commands can also be used as execution options.

- `comp_elim/nocomp_elim` (default: `comp_elim`): to activate/deactivate complete rewriting of `comp` constraints; using `nocomp_elim` may make the solver incomplete.
- `fix_size/nofix_size` (default: `nofix_size`): to activate/deactivate fixed set cardinality mode for size constraint solving.
- `int_solver(S)`, $S = \text{clpq} \mid \text{clpfd}$ (default: `clpq`): to select the integer constraint solver.
- `irules/noirules` (default: `irules`): to activate/deactivate inference rules.
- `label/nolabel` (default: `label`): to activate/deactivate labeling on integer variables.
- `mode(M)`, $M = \text{prover} \mid \text{solver} \mid \text{prover}([\text{opt}_1, \dots, \text{opt}_n])$: to change the solver operation mode. In turn, `opt_i` is a prover option (see below).
- `neq_elim/noneq_elim` (default: `neq_elim`): to activate/deactivate `neq` elimination; using `noneq_elim` may make the solver incomplete.
- `ran_elim/noran_elim` (default: `ran_elim`): to activate/deactivate complete rewriting of `ran` constraints; using `noran_elim` may make the solver incomplete.
- `strategy(Str)`, $\text{Str} = \text{cfirst} \mid \text{ordered} \mid \text{cfirst}(\text{list_of_preds})$: to change goal predicate selection strategy to `Str`
- `show_min/noshow_min` (default: `noshow_min`): to activate/deactivate showing minimal set cardinalities making the input formula satisfiable
- `trace(T)/notrace`, $T = \text{sat} \mid \text{irules}$ (default: `notrace`): to deactivate/activate constraint solving tracing
- `type_check/notype_check` (default: `notype_check`): to activate/deactivate $\{log\}$ type-checking (see Sect. 12).
- `groundsol/nogroundsol` (default: `nogroundsol`): to activate/deactivate the computation of ground solutions (see Sect. 3.2).

The prover options are those listed in Table 10. Any prover option is also an execution option.